Enhancing Approximate Conformance Checking Accuracy with Hierarchical Clustering Model Behaviour Sampling

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Abstract

Conformance checking techniques evaluate how well a process model aligns with an actual event log. Existing methods, which rely on optimal trace alignment, are computationally intensive. To improve efficiency, a model sampling method has been proposed to construct model behaviour subset that represents the entire model. However, current model sampling techniques often lack sufficient model representativeness, limiting their potential to achieve optimal approximation accuracy. This paper proposes new model behaviour sampling approaches using hierarchical clustering to compute an approximation closer to the exact result. This paper also refines existing upper bound algorithm for better approximation. Our experiments on six real-world event logs demonstrates that our method improves approximation accuracy compared to state-of-the-art model sampling methods.

Keywords: approximate conformance checking, model behaviour sampling, hierarchical clustering, process mining

1. INTRODUCTION

Conformance checking is a set of process mining functionalities aimed at identifying deviations between the actual behaviour of the event log ("as-is") and the modeled behaviour of the process model ("to-be"). It facilitates further applications, such as model repair, anomaly detection, and algorithm evaluation [\[1\]](#page-7-0).

In recent years, alignment-based method [\[2\]](#page-7-1) has become the de facto standard for conformance checking in computing conformance diagnostics, as it always returns the most accurate deviations, known as optimal-alignment [\[3\]](#page-7-2). However, finding the optimal alignment is an NP-hard problem [\[4\]](#page-7-3). As the complexity of the log and model increases, the runtime complexity of optimal alignment computation grows exponentially, leading to extremely long computation times—sometimes even taking several weeks. This makes them impractical for real-world applications, especially for large-scale event logs. Moreover, in certain cases, an exact conformance value is not necessary, such as when conducting a preliminary evaluation of process models with various process discovery algorithm [\[5\]](#page-7-4).

To tackle the problems, various approximation strategies have been proposed, including optimizing the search algorithm [\[6,](#page-7-5) [7\]](#page-7-6) and decomposition schemes [\[8,](#page-7-7) [9\]](#page-7-8). However, sampling provides another angle for approximate conformance checking, such as sampling traces to represent event log [\[10,](#page-7-9) [11\]](#page-8-0) or selecting model traces to substitute process model [\[5,](#page-7-4) [12\]](#page-8-1). In this paper, we adopt the latter approach, focusing on model sampling. Two main model sampling methods exist: simulation [\[13\]](#page-8-2) and candidate selection [\[5\]](#page-7-4). We concentrate on candidate selection due to its higher accuracy [\[5\]](#page-7-4). The candidate selection method identifies representative traces from the event log (i.e. log behaviour subset), and then computes their optimal alignments to determine the corresponding model traces (i.e., model behaviour subset). The accuracy of this approximation depends on the quality of the selected log traces [\[12\]](#page-8-1). However, existing log selection

techniques (e.g., random, frequency-based [\[5\]](#page-7-4), K-Medoids [\[14\]](#page-8-3)) often lack behavioural diversity and model representativeness (see Section [2\)](#page-0-0), leading to reduced accuracy in conformance approximation. Hence, there is significant potential for improving the quality of model behaviour subsets.

In this paper, we propose an enhanced model behaviour sampling method to select more representative subsets and get more accuracy approximate values. First, we apply hierarchical clustering to the event log using our proposed distance criterion. Then, we propose two in-cluster methods to select typical traces from each cluster, which are then used to construct more representative model behaviour subsets. Finally, we extend existing cost lower bound algorithm to achieve more accurate approximation results. The experimental results show that our approach yields more accurate approximations than existing baselines, though with increased approximation time.

The remainder of this paper is organized as follows: Section [2](#page-0-0) provides a motivating example to further illustrate the research problem. Section [3](#page-1-0) discusses related work in approximate conformance checking. Section [4](#page-1-1) outlines the necessary preliminaries. In Section [5,](#page-2-0) we propose our method for constructing model behaviour subsets using hierarchical clustering. Section [6](#page-5-0) details the evaluation and its results. Finally, Section [7](#page-7-10) concludes the paper and presents the future work.

2. MOTIVATING EXAMPLE

Research such as [\[5\]](#page-7-4) and [\[15\]](#page-8-4) has shown that selecting more typical log traces lead to higher approximation accuracy. Thus, the key challenge is determining which subset should be selected to improve approximate accuracy. Existing log selection methods, such as the frequency-based and K-medoids approaches, sometimes lack sufficient log representativeness.

To illustrate the potential limitations of these methods, we use a synthesized event log *L*. It contains 5,106 traces consisting of 32,600 events and 12 trace variants, as shown in Table [1.](#page-1-2)

Table 1: Event Log

Trace Variant	Freq	m	Trace Variant	Freq
$\langle a,b,c,d,f,e,g,h \rangle$	1280	6	$\langle a, d, f, h \rangle$	250
$\langle a, b, c, d, e, f, g, h \rangle$	912		$\langle a, f, b, c \rangle$	96
$\langle a, b, c, d, e, g, f, h \rangle$	864	8	$\langle a,c,e,f,g \rangle$	64
$\langle a,b,c,h \rangle$	792	9	$\langle a, d, e, g, h \rangle$	56
$\langle a, b, c, d, h \rangle$	400	10	$\langle a,b,f,e,g,h \rangle$	48
$\langle a, h \rangle$	320	11	$\langle b, f, g \rangle$	24

To discover the event log presented in Figure [1,](#page-1-3) we applied the Inductive Miner algorithm [\[16\]](#page-8-5) with infrequent thresholds of 0.9.

Figure 1: The Process Model discovered by Inductive Miner with infrequent threshold equals to 0.9.

Assuming we select three variants to represent the event log, i.e., the behavior subset consists of three variants. Table [2](#page-1-4) shows the behaviour subsets generated by the frequency-based method, K-Medoids, and our proposed methods (see Section [5](#page-2-0) for details). The frequency-based subsets shows two key limitations:

- 1. Overestimation of Alignment Cost: Variant 5, ⟨*a*, *^h*⟩, can be perfectly replayed in the model with an alignment cost of 0. But it's not included in our model behaviour subset, aligning it would require at least 6 insertions (i.e., cost of 6), resulting in an overestimated approximate cost.
- 2. Lack of Structural Diversity: The selected model traces $\langle a, b, c, d, f, e, g, h \rangle$ and $\langle a, b, c, d, e, f, g, h \rangle$ differ only in the order of *e* and *f* . This means they represent essentially the similar structural path, potentially overlooking other important paths in the process model.

Also, the K-Medoids method has drawbacks: it clusters traces solely based on their control-flow information, i.e., syntactic difference. For example, the trace $\langle b, f, g \rangle$ in log behaviour subset (as shown in Table [2\)](#page-1-4) may have significantly syntactic differences from other traces but, due to its low frequency (only 24 occurrences), it is still not enough to represent the model behaviour.

To address the issues, our approach proposed in Section [5](#page-2-0) effectively balances frequency and control-flow information. Table [2](#page-1-4) also shows the cost deviation. It refers to the difference in alignment cost between using model behaviour subset and optimal-alignment. The values indicate that the model behaviours generated by our methods significantly reduce the cost deviations compared to vanilla methods.

Table 2: behaviour subsets constructed by four methods

Method	Subset	Result	Cost Deviation	
Frequency- based	Log Behaviour	$\Sigma_L = \{ \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, d, e, f, g, h \rangle, \}$ (a, b, c, d, e, e, f, h)	7806	
	Model Behaviour	$\Sigma_M = \{ \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, d, e, f, g, h \rangle, \}$ (a, b, c, d, e, e, f, h)		
K-Medoids	Log Behaviour	$\Sigma_I = \{ \langle a, h \rangle, \langle a, b, c, d, e, e, f, h \rangle, \}$ $\langle b, f, g \rangle$	6596	
	Model Behaviour	$\Sigma_{\mathcal{M}} = \{ \langle a, h \rangle, \langle a, b, c, d, e, g, f, h \rangle, \}$ (a, b, e, f, g, h)		
In-cluster frequency	Log Behaviour	$\Sigma_l = \{(a, h), (a, b, c, d, f, e, g, h), (a, b, c, h)\}\$	4698	
	Model Behaviour	$\Sigma_M = \{ \langle a, h \rangle, \langle a, b, c, d, f, e, g, h \rangle \}$ (a, b, c, h)		
In-cluster medoid	Log Behaviour	$\Sigma_I = \{(a, d, f, h), (a, b, c, d, f, e, e, h), (a, b, c, h)\}\$	4854	
	Model Behaviour	$\Sigma_M = \{ \langle a, d, h \rangle, \langle a, b, c, d, f, e, g, h \rangle \}$ $\langle a,b,c,h \rangle$		

3. RELATED WORK

To cope with the complexity of alignment construction, approximation techniques have been developed to balance result quality and computational cost. One approach explores fast heuristic search algorithms as alternatives to the A* algorithm [\[7,](#page-7-6) [17,](#page-8-6) [18\]](#page-8-7). replace the A^* algorithm by exploring new fast heuristic search algorithms. One such method is Taymouri and Carmona [\[17\]](#page-8-6), introducing an evolutionary algorithm to enhance alignment approximations. Another scheme involves decomposing models into smaller, more manageable parts, even though this may not always result in optimal alignments [\[19,](#page-8-8) [20\]](#page-8-9). A similar decomposition technique is discussed in [\[21\]](#page-8-10), though it is restricted to sound and safe workflow nets. Furthermore, building automata capable of aligning log and model has been explored as another technique [\[22,](#page-8-11) [23\]](#page-8-12). This approach provides good approximations of the optimal alignments in most cases.

Reducing the behaviour size is another strategy for approximate conformance checking. One sampling approach focuses on sampling event log. For instance, [\[24\]](#page-8-13) proposes a trace sampling method, assuming that a few log traces can estimate the conformance value. However, it lacks upper and lower bounds for the approximation and performs worse when the event log contains many unique behaviors.

Another sampling approach targets model behaviour. [\[5\]](#page-7-4) introduced a model sampling method to construct subsets of model behaviour that represent the whole process model, significantly reducing approximation time while largely maintaining accuracy. The method also provides upper and lower bounds to give some certainty of the approximation.

Hierarchical clustering is widely used in process mining for its structural representativeness [\[25\]](#page-8-14). Additionally, [\[26\]](#page-8-15) demonstrates how hierarchical clustering aids in discovering a better model.

4. PRELIMINARIES

This section presents conformance checking terminology and notations to support the subsequent sections. We use the basic definitions of Petri net, e.g., labeled Petri Net in [\[27\]](#page-8-16).

Given a system net *SN*, $\phi_f(SN)$ is the set of all complete firing sequences of *SN* and $\phi_{\nu}(SN)$ is the set of all possible visible traces, i.e., complete firing sequences starting in its initial marking and ending in its final marking projected onto the set of observable activities (not silent transitions e.g., *t*³ in Figure [1\)](#page-1-3).

To measure how a trace aligns to a process model, moves are represented by pairs (a, t) , where a is a log activity and t is a model transition. Legal moves can be: *log moves* , *model moves*, or *synchronous moves* . Any other combination is an *illegal move*.

Definition 1. *(Alignment). Let* $\sigma_L \in L$ *represent a log trace and* ^σ*^M* [∈] ^ϕ*f*(*S N*) *denote a complete firing sequence of a system net SN.* A_{LM} *is the set of legal moves. An alignment of* σ_L *and* σ_M *is a sequence of pairs* $\gamma \in A^*_{LM}$ *such that the projection on the*
first element (ignoring \gg) *yields* σ *r*, and the projection on the *first element (ignoring* ≫*)* yields $σ$ _{*L*} *and the projection on the second element (ignoring* \gg *and transition labels) yields* σ_M *.*

To quantify the costs of alignments we introduce a cost function δ in Definition [2.](#page-2-1)

Definition 2. *(Cost of Alignment). Cost function* $\delta \in A_{LM} \to \mathbb{N}$ *assigns costs to legal moves. The cost of an alignment* $\gamma \in A_{LM}^*$
is the sum of all costs: is the sum of all costs:

$$
\delta(\gamma) = \sum_{(a,t)\in\gamma} \delta(a,t).
$$

The cost values assigned to log moves, model moves, and synchronous moves are 1, 1, and 0, respectively. Note that an alignment is considered optimal if it has the minimum alignment cost.

Definition 3. *(Optimal Alignment). Let L be an event log and SN a system net where* $\phi_v(SN) \neq \emptyset$ *.*

- *For* $\sigma_L \in L$, we define: $\Gamma_{\sigma_L,SN} \in \{ \gamma \in A_{LM}^* \mid \exists \sigma_M \in A_{CM}^{\leq N} \}$ $\phi_f(SN)$ *is an alignment of* σ_L *and* σ_M *).*
- An alignment $\gamma \in \Gamma_{\sigma_L, SN}$ *is optimal for trace* $\sigma_L \in L$ *and system net SN if for any alignment* $\gamma' \in \Gamma_{\sigma_L, M}$ *:* $\delta(\gamma') \ge \delta(\gamma)$ δ(γ)*.*
- $\gamma_{SN} \in A_{LM}^* \to A_{LM}^*$ is a mapping that assigns any log trace
 σ_Y to an optimal alignment i.e., $\gamma_{SN}(\sigma_Y) \in \Gamma$, so and σ_L *to an optimal alignment, i.e.,* $\gamma_{SN}(\sigma_L) \in \Gamma_{\sigma_L,SN}$ *and* $\gamma_{SN}(\sigma_L)$ *is an optimal alignment.*

Definition 4. *(Levenshtein Edit Distance). As defined by [\[28\]](#page-8-17), the Levenshtein edit distance* $d(\sigma_1, \sigma_2) \rightarrow \mathbb{N}$ *represents the minimum number of edit operations (i.e., insertions, deletions, and substitutions) required to transform one sequence into another. For instance,* $d(\langle a, b \rangle, \langle c, d \rangle) = 2$, where the two edit operations *are substitutions* (*a*, *^c*) *and* (*b*, *^d*)*.*

Definition 5. *(Edit Distance Cost Function). We can calculate the distance between two traces (or sequences) faster by using a modified version of the Levenshtein edit distance [\[29\]](#page-8-18). Let* $\sigma_1, \sigma_2 \in A^*$ *be two sequences of activities. The Edit Distance*
Cost Function $\Lambda(\sigma_1, \sigma_2) \to \mathbb{N}$ is defined as the minimum number *Cost Function* $\Delta(\sigma_1, \sigma_2) \rightarrow \mathbb{N}$ *is defined as the minimum number of edits (insertion or deletion of activities) required to transform* σ_1 *into* σ_2 .

Suppose that S is a set of sequences, $\Phi(\sigma_L, S)$ = $\min_{\sigma_M \in S} \Delta(\sigma_L, \sigma_M)$ *returns the distance of the most similar seguence in S. Let* $\phi_v(SN)$ *be the set of all visible firing sequences*

in SN, and $\gamma_{SN}(\sigma)$ *be an optimal alignment for sequence* σ *. It is possible to prove that* $\delta_S(\gamma_{SN}(\sigma)) = \Phi(\sigma, \phi_v(SN))$ [\[12\]](#page-8-1)*.*

In the context of alignment, the edit distance function can be used as a cost function δ_S for evaluating the misalignment between a log trace σ_L and a model trace σ_M . This cost function assigns a value corresponding to the number of operations required to align the two sequences. For example, $\Delta(\langle a, c, b, e, d \rangle, \langle a, b, c, a, d \rangle) = 4$ corresponds to two deletions and two insertions.

Moreover, the alignment cost of a single trace can be converted into a fitness value between 0 (poor fitness, i.e., maximal costs) and 1 (perfect fitness, i.e., zero costs) using Equation [1](#page-2-2) [\[5\]](#page-7-4). In this regard, we normalize this cost relative to the worst case, with one log move for each activity in the trace and one model move for each transition in the model's shortest path, $SPM = \min_{\sigma_M \in \phi_f}(|\sigma_M|)$. Here, the optimal alignment
cost $\delta(x_{\text{c}} \cdot \sigma(x))$ can be replaced by an alternative cost (e.g. edition cost, $\delta(\gamma_{SN}(\sigma))$, can be replaced by an alternative cost (e.g., edit distance cost) to obtain a corresponding fitness value.

$$
Fitness_{Trace}(\sigma_L, SN) = 1 - \frac{\delta_S(\gamma_{SN}(\sigma))}{|\sigma_L| + SPM}
$$
 (1)

Note that the overall fitness between the event log and the system net is the weighted average of single trace fitness values.

5. APPROACH

In this section, we present the proposed conformance approximation method. An overview of our approach is shown in Figure [2.](#page-3-0) The method begins with a preprocessing stage using hierarchical clustering techniques. Next, two methods are proposed for constructing model behaviour subsets: in-cluster frequency and in-cluster medoid methods. Finally, the alignment approximation process is explained.

5.1. Preprocess event log using hierarchical clustering

In this stage, we apply agglomerative hierarchical clustering [\[30\]](#page-8-19) on event logs. Specifically, we first partition the event log based on trace variants to get the trace variant subset Σ_{σ_v} .
Then we introduce permelized weighted Lavanchtein distance to Then, we introduce normalized weighted Levenshtein distance to measure the distance between these variants(see Definition [6\)](#page-2-3) as a new in-cluster distance criterion. This criterion considers both frequency and control-flow information, alleviating the problem with current log selection methods mentioned in Section [2.](#page-0-0) It is used to build a distance matrix, then forming a dendrogram. By cutting-off the dendrogram, we obtain the desired number of clusters. The framework is illustrated in Figure [3.](#page-3-1)

Definition 6. *(Normalized Weighted Levenshtein Distance). Let A* [∗] *be the set of all possible sequences of activities in A, and let* σ_{v1}, σ_{v2} *be two trace variants* \in *A*^{*}. *The normalized weighted Levenshtein distance between* σ , and σ , where each trace *Levenshtein distance between* σ_{v1} *and* σ_{v2} *, where each trace variant has a frequency* $f(\sigma_{v1})$ *and* $f(\sigma_{v2})$ *, is defined as:*

$$
d_{weighted}(\sigma_{v1}, \sigma_{v2}) = \frac{f(\sigma_{v1}) \cdot f(\sigma_{v2}) \cdot d_N(\sigma_{v1}, \sigma_{v2})}{\max\{f(\sigma_{v1})^2, f(\sigma_{v2})^2\}} \qquad (2)
$$

Figure 2: Overview of our approach

Figure 3: Preprocessing workflow for hierarchical clustering

where the normalized Levenshtein distance $d_N(\sigma_{v1}, \sigma_{v2})$ *is given by:*

$$
d_N(\sigma_{\nu 1}, \sigma_{\nu 2}) = \frac{d(\sigma_{\nu 1}, \sigma_{\nu 2})}{\max\{|\sigma_{\nu 1}|, |\sigma_{\nu 2}|\}}
$$
(3)

Here, $d_N(\sigma_{\nu_1}, \sigma_{\nu_2}) = 0$ *means the two traces are exactly the same, and* $d_N(\sigma_{v1}, \sigma_{v2}) = 1$ *means the two traces are completely di*ff*erent.*

Definition 7. *(Distance Matrix). Let* $\sigma_{v1}, \sigma_{v2}, \ldots, \sigma_{vi} \in A^*$
represent all trace variants in event log I. The matrix D(I) is represent all trace variants in event log L. The matrix D(*L*) *is defined as, :*

$$
D(L) = \begin{bmatrix} 0 & d(\sigma_{v1}, \sigma_{v2}) & \cdots & d(\sigma_{v1}, \sigma_{vi}) \\ d(\sigma_{v2}, \sigma_{v1}) & 0 & \cdots & d(\sigma_{v2}, \sigma_{vi}) \\ \vdots & \vdots & \ddots & \vdots \\ d(\sigma_{vi}, \sigma_{v1}) & d(\sigma_{vi}, \sigma_{v2}) & \cdots & 0 \end{bmatrix}
$$
 (4)

where d is the normalized weighted Levenshtein distance function.

5.2. Constructing Model Behaviour

In this stage, we first propose two in-cluster methods to get log behaviour subset Σ_L from the generated clusters, and transform it to model behaviour subset Σ_M . Specifically,

a) Candidate selection: After preprocessing, we obtain several clusters, each representing different behaviours within the model. The following question is how to choose the typical traces from each cluster to construct a better log behaviour subset. We extend the ideas of frequency-based and medoid methods by introducing two in-cluster methods, i.e., in-cluster frequency and in-cluster medoid methods, to select trace that represents typical behaviour in each cluster as our candidate. The in-cluster frequency method selects the most frequent trace variant from each cluster. The in-cluster medoid method computes the pairwise Levenshtein distances between all traces in each cluster, then construct a distance matrix and obtain the medoid trace (see Definition [8\)](#page-3-2). Note that the medoid trace is the one with the smallest total distance to all other traces in the cluster.

b) Optimal-alignment: In this step, we align Σ_L with process model to construct the Σ_M , that is, we compute the optimal alignments of selected traces in the event log and finding the corresponding model traces for these alignments.

Table [3](#page-3-3) shows three clusters generated from the event log in Table [1.](#page-1-2) For example, applying the in-cluster frequency method to cluster 2 yields $\langle a, b, c, h \rangle^{792}$, the most frequent
trace. Repeating this for each cluster, we obtain Σ_{γ} . trace. Repeating this for each cluster, we obtain Σ*^L* = { $\langle a, b, c, d, f, e, g, h \rangle$ ¹²⁸⁰, $\langle a, b, c, h \rangle^{792}$, $\langle a, h \rangle^{320}$ }. We then align
 Σ_t , with the process model as shown in Figure 1, resulting in Σ_L with the process model as shown in Figure [1,](#page-1-3) resulting in Σ_M . Note that Σ_L and Σ_M are same in this example, as all traces can be fully replayed in the model.

Table 3: The clusters generated from the example log provided in Table [1](#page-1-2)

Cluster ID	Traces in each cluster
	$\{(a, b, c, d, f, e, g, h)^{1280}, (a, b, c, d, e, f, g, h)^{912}, (a, b, c, d, e, f, g, h)^{864}\}\$
	$\{(a, b, c, h)^{792}, (a, b, c, d, h)^{400}, (a, f, b, c)^{96}\}\$
	$\{\langle a, h \rangle^{320}, \langle a, d, h \rangle^{250}, \langle a, c, e, f, g \rangle^{64},\}$ $\langle a, d, e, g, h \rangle^{56}, \langle a, b, f, e, g, h \rangle^{48}, \langle b, f, g \rangle^{24}$

The specific algorithm steps for proposed methods are outlined in Algorithms [1](#page-4-0) and [2.](#page-4-1)

Definition 8. *(In-cluster Medoid). Let L* ′ *be a clustered sublog, n denote the number of trace variants in L* ′ *, and D*(*L* ′) *be the distance matrix of L'*. The trace $\sigma_j = \arg \min_{\sigma_j \in L'} \sum_{i \in [1,n]} d(\sigma_i, \sigma_j)$
represents the medoid trace of sublog I' *represents the medoid trace of sublog L*′ *.*

5.3. Computing Alignment Approximation

After constructing M_B , we use it to approximate alignments for the traces in $L - L_C$, where L_C refers to the frequency-based trace variants used to build Σ_L . The actual alignment fitness for the variants in Σ_L has already been computed during the construction of M_B , so we can directly use this value for more accurate approximations. At this stage, we calculate the alignment approximations for the remaining variants.

Typically, actual fitness is calculated using standard alignment costs. However, for the remaining variants, we use the edit distance cost function Δ (see Definition [5\)](#page-2-4) to estimate fitness.

Algorithm 1 In-cluster Medoid Method

Input: Event log *L*; Process model *M*.

- Output: Model behaviour subset Σ*M*.
- 1: Initialize log behaviour subset: Σ*^L* ← ∅
- 2: Initialize model behaviour subset: $\Sigma_M \leftarrow \emptyset$
- 3: Partition *L* based on variants into Σ_{σ_v}
- 4: Cluster Σ_{σ_v} into *k* clusters $\{\Sigma_{\sigma_{v1}}, \Sigma_{\sigma_{v2}}, \dots, \Sigma_{\sigma_{vk}}\}$ using hierar-
chical clustering chical clustering
- 5: for $i = 1$ to k do
- 6: Compute pairwise Levenshtein distances between all variants in $\Sigma_{\sigma_{vi}}$
- 7: Construct distance matrix $D(\Sigma_{\sigma_{vi}})$
8: Find the medoid trace $\sigma_{v}^{(i)}$ in Σ_{σ} .
- 8: Find the medoid trace $\sigma_L^{(i)}$ in $\Sigma_{\sigma_{vi}}$:

$$
\sigma_L^{(i)} = \arg\min_{\sigma \in \Sigma_{\sigma_{vi}}} \sum_{\sigma' \in \Sigma_{\sigma_{vi}}} d(\sigma, \sigma')
$$

- 9: Update log behaviour subset: $\Sigma_L \leftarrow \Sigma_L \cup \{\sigma_L^{(i)}\}$
- 10: end for
- 11: **for** each $\sigma_L^{(i)} \in \Sigma_L$ **do**
12. **Compute online**
- 12: Compute optimal alignment γ_{SN}^{opt} between $\sigma_L^{(i)}$ and *M*
- 13: Map to model trace: $\sigma_M^{(i)} \leftarrow \lambda_{SN}(\sigma_L^{(i)})$
 M and the model behaviour subsets Σ 14: Update model behaviour subset: $\Sigma_M \leftarrow \Sigma_M \cup \{\sigma_M^{(i)}\}$
15: end for
- 15: end for
- 16: return Σ*^M*

Algorithm 2 In-cluster Frequency Method

Input: Event log *L*; Process model *M*.

Output: Model behaviour subset Σ*M*.

1: Initialize log behaviour subset: Σ*^L* ← ∅

- 2: Initialize model behaviour subset: $\Sigma_M \leftarrow \emptyset$
- 3: Partition *L* based on variants into Σ_{σ_v}
- 4: Cluster Σ_{σ_v} into *k* clusters $\{\Sigma_{\sigma_{v1}}, \Sigma_{\sigma_{v2}}, \dots, \Sigma_{\sigma_{vk}}\}$ using hierar-
chical clustering chical clustering
- 5: for $i = 1$ to k do
- 6: Let $\Sigma_{\sigma_{vi}}$ denote the *i*-th cluster of variants
7: Find the most frequent variant $\sigma_i^{(i)}$ in Σ_{σ} .
- 7: Find the most frequent variant $\sigma_L^{(i)}$ in $\Sigma_{\sigma_{\nu i}}$:

$$
\sigma_L^{(i)} = \arg\max_{\sigma \in \Sigma_{\sigma_{vi}}} f(\sigma)
$$

- 8: Update log behaviour subset: $\Sigma_L \leftarrow \Sigma_L \cup \{\sigma_L^{(i)}\}$ 9: end for
- 10: **for** each $\sigma_L^{(i)} \in \Sigma_L$ **do**

11: Compute optimal alignment
$$
\gamma_{SN}^{\text{opt}}
$$
 between $\sigma_L^{(i)}$ and M

- 12: Map to model trace: $\sigma_M^{(i)} \leftarrow \lambda_{SN}(\sigma_L^{(i)})$
 Map to model behaviour wheat: Σ
- 13: Update model behaviour subset: $\Sigma_M \leftarrow \Sigma_M \cup \{\sigma_M^{(i)}\}$
- 14: end for
- 15: return Σ*^M*

This method provides guaranteed upper and lower bounds for the alignment cost, instead of exact values [\[5\]](#page-7-4) (see Lemma [1](#page-4-2) and Lemma [2](#page-4-3) below).

$$
Fitness(L, SN) = \frac{\sum_{\sigma \in L_C} f(\sigma) \times Fitness_{Approximate}(\sigma, SN)}{\sum_{\sigma \in L} f(\sigma)} + \frac{\sum_{\sigma \in L - L_C} f(\sigma) \times Fitness_{Actual}(\sigma, SN)}{\sum_{\sigma \in L} f(\sigma)}
$$
(5)

Lemma 1 (Alignment Cost Upper Bound). *Let* $\sigma_L \in \mathcal{U}_A^*$ be a log trace and $\sigma_U \in \mathcal{A}(SN)$ be a visible firing sequence of *a log trace and* $\sigma_M \in \phi_v(SN)$ *be a visible firing sequence of SN. We have* $\delta_S(\gamma_{SN}(\sigma_L)) \leq \Delta(\sigma_L, \sigma_M)$ *, where* $\gamma_{SN}(\sigma_L)$ *is the optimal alignment.*

Proof. The proof is provided in [Appendix A.1](#page-8-20) and demonstrates how the edit distance guarantees this upper bound.

Simply put, if we align trace variant $4 \langle a, b, c, d, h \rangle$ from Table [1](#page-1-2) with σ_L from the in-cluster frequency subset in Table [2,](#page-1-4) the alignment cost is 1 (i.e., removing "d"). However, since σ_M is a subset of the full model, the actual cost could be smaller or equal. Thus, we use 1 as the upper bound for this variant.

Lemma 2 (Alignment Cost Lower Bound). *Let S PM* = $\min_{\sigma_M \in \phi_v(SN)} |\sigma_M|$ and $LPM = \max_{\sigma_M \in \phi_v(SN)} |\sigma_M|$, representing
the shortest and longest paths in the process model M, σ -L, car *the shortest and longest paths in the process model M.* σ_L $\left[\frac{A_v(S_N)}{A_v(S_N)} \right]$ *and* $\kappa(\sigma_L)$ *are as defined in Definition [9.](#page-5-1)*

For any log trace σ_L *, if* $|\sigma_L|_{A_v(S,N)} < SPM$, the alignment *st lower bound is* $SPM - |\sigma_L|_{L_v(S,N)} + \kappa(\sigma_L) \cdot i f(\sigma_L)_{L_v(S,N)}$ *cost lower bound is* $SPM - |\sigma_L[A_{\nu}(S_N)| + \kappa(\sigma_L);$ *if* $|\sigma_L[A_{\nu}(S_N)| >$
LPM the lower bound is $|\sigma_L[\cdot, \infty) - LPM + \nu(\sigma_L);$ if $SPM <$ *LPM, the lower bound is* $|\sigma_L|_{A_v(SN)} - LPM + \kappa(\sigma_L)$; *if* $SPM \leq$ $|\sigma_L$ $\lceil_{A_v(SN)}| \leq LPM$, the lower bound is $\kappa(\sigma_L)$ *.*

Proof. The proof is provided in [Appendix A.2.](#page-8-21)

The cost lower bound is the minimum edit operations needed to transform σ_L into σ_M . We refine this algorithm using activity projection (see Definition [9\)](#page-5-1) to improve approximation accuracy. Existing methods compare log trace length directly with the model's range, potentially yielding errors if irrelevant activities are present. For instance, in Figure [1,](#page-1-3) a trace $\langle a, x \rangle$ might seem aligned if its length falls within the model's shortest (SPM=2) and longest paths (LPM=8), even though x is not in the model, resulting in a miscalculated cost of 0. Our algorithm removes non-model activities (e.g., removing *x* from $\langle a, x \rangle$ to form $\langle a \rangle$) before comparing trace lengths. This adjustment yields a more accurate cost of 1 rather than 0, resulting in a smaller upper fitness and tighter bound width.

These bounds are then used to compute corresponding upper and lower fitness bounds (with the cost upper bound giving the fitness lower bound, and vice versa) using Equation [1.](#page-2-2) The computations for the fitness bounds are provided in Algorithm [3](#page-5-2) and [4.](#page-5-3) The average of these bounds provides the approximate fitness. Once we compute the approximate fitness for each remaining variant, we take the weighted average of these values along with the previously computed actual fitness to get the overall approximate fitness for the entire event log, as shown in Equation [5.](#page-4-4)

Definition 9 (Activity Projection). *Let Av*(*S N*) *be the set of unique observable activities in the system net S N. For any log trace* ^σ*^L, let* ^σ*L*⌈*Av*(*S N*) *represent the projection of* ^σ*^L onto* $A_v(SN)$, meaning the set of activities in σ_L that also appear in *the model. Define* $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L| \int_{A_v(S_N)} ds$ *as the number of activities in* σ_t , *that are not present in the model activities in* σ_L *that are not present in the model.*

For example, let $\sigma_L = \langle a, b, x \rangle$ be a log trace and the observable activities of the system net be $A_v(SN) = \{a, b, c, d, e\}$. Projecting σ_L onto $A_\nu(SN)$ results in $\sigma_L[\Lambda_\nu(SN)] = \langle a, b \rangle$, as *x* is not part of $A_v(SN)$. Therefore, $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L| [A_v(sN)] = 3 - 2 = 1$, indicating one activity in σ_L is not present in the model.

Algorithm 4 Fitness upper bound computation

Input: Event log *L*; Optimal-aligned Log *LC*; Model behaviour subset Σ*M*. **Output:** Upper bound fitness U *f itness*(σ *L, M*). 1: *SPM* ← min_{σ*M*}∈ $\phi_{\nu}(SN)$ |*o*_{*M*}| // Shortest path
2: *IPM* ← may a sear |o v| // Longest path 2: $LPM \leftarrow \max_{\sigma_M \in \phi_v(SN)} |\sigma_M| / |\text{Longest path}$
3: for each $\sigma_v \in I - I \circ \text{do}$ 3: **for** each $\sigma_L \in L - L_C$ **do**
4: **Project** σ_I onto *SN*: 4: Project σ_L onto *SN*: $\sigma_L\lceil_{A_v(SN)}$
5: Compute $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L|$ _{*A*} 5: Compute $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L| \leq \int_{A_V(S)} |\sigma_L| \leq \int_{A_V(S)} f$ film | 6: **if** $|\sigma_L|_{A_v(SN)}| < SPM$ then
7: $U_fitness(\sigma_L, M) \leftarrow 1$ $| < SPM$ then 7: $U_{-}f$ *itness*(σ_{L}, M) ← 1 – $\frac{SPM - |\sigma_{L}|_{A_{\gamma}(S,N)}| + \kappa(\sigma_{L})}{|\sigma_{L}| + \min_{\sigma_{M} \in \phi_{\gamma}(S,N)}(|\sigma_{M}|)}$ $|\sigma_L|$ +min_{$\sigma_M \in \phi_V(SN)}(|\sigma_M|)$} 8: **else if** $|\sigma_L|_{A_v(S,N)} > LPM$ then
9: $U_fitness(\sigma_L, M) \leftarrow 1 - \frac{|\sigma|}{L}$ $| > LPM$ then 9: $U_fitness(\sigma_L, M) \leftarrow 1 - \frac{|\sigma_L|_{A_V(S,N)}| - LPM + \kappa(\sigma_L)}{|\sigma_L| + \min_{\sigma_M \in \phi_V(S,N)}(|\sigma_M|)}$ $|\sigma_L|$ +min_{$\sigma_M \in \phi_V(SN)}(|\sigma_M|)$} 10: else 11: $U_{-}f$ *itness*(σ_{L}, M) ← 1 – $\frac{k(\sigma_{L})}{|\sigma_{L}|+\min_{\sigma_{M} \in \phi_{V}(S/N)}(|\sigma_{M}|)}$ 12: end if 13: end for 14: **return** U _{*f*} *itness*(σ _{*L*}, *M*)

6. EVALUATION

In this section, we assess the accuracy and time performance of our proposed log selection methods compared to frequencybased and K-Medoids techniques, and evaluate their differences in accuracy and time against normal alignment. Note that the comparison between model behaviour sampling and other approximate methods has been discussed in [\[5\]](#page-7-4), we focus here on comparisons with the baselines of model behaviour sampling. First, we briefly describe the implementation (Section [6.1\)](#page-5-4) and experimental setup (Section [6.2\)](#page-5-5), followed by a discussion of the experimental results (Section 6.3).

6.1. Implementation

Our implementation consists of two steps: first, we implemented the algorithms described in Sections [5.1](#page-2-5) and [5.2](#page-3-4) in Python, to generate log behaviour subset from event log. Specifically, we extended the pm4py.algo.clustering package in PM4py [\[31\]](#page-8-22) by introducing the normalized weighted Levenshtein distance (Definition [6\)](#page-2-3), to perform hierarchical clustering. And implemented two proposed in-cluster methods to get the log behaviour subset based on the clustering result. In the second step, we used an existing plugin in ProM [\[32\]](#page-8-23), *Conformance Log to Log Approximation* [\[33\]](#page-8-24), with the generated model behaviour subset and the original event log as input, obtaining approximate fitness bounds and values. For the baselines, we used the implementation proposed by Fanisani [\[5\]](#page-7-4). For the normal alignment, we used PM4py to compute the time and fitness values. The source code and experimental results is available on Github^{[1](#page-5-6)}.

6.2. Experimental Setup

Our experiments were based on six real event logs, with the basic information about these event logs is given in Table [4.](#page-5-7) Here, *Uniqueness* refers to $\frac{\text{Variant}\#}{\text{Trace}}$. A *Uniqueness* value close to 1 indicates that almost all traces are different, e.g., *Sepsis*. For process discovery, we used *Inductive Miner infrequent algorithm* [\[34\]](#page-8-25) with *infrequent thresholds of 0.4* to get the process model . Two log selection methods, *frequency-based sampling*, *K-Medoids clustering*, were used as baselines to compare with our proposed methods, i.e., *In-cluster frequency method* and *In-cluster medoid method*. Additionally, we set the *selection percentage* to 10%, 20%, 30%, 40%, and 50%, representing the ratio of selected variants to the total number of variants in the event logs. Our experiment was repeated four times since the conformance approximation time is non-deterministic. Finally, we performed the experiments on a computer with Apple M1 (8

6.2.1. Evaluation Metrics

cores), 8 GB RAM running macOS.

To measure approximation accuracy, we used *Approximate Error*, defined as *ApproximateError* = |*ActualFitness* − *ApproximateFitness*|, where a value closer to 0 indicates higher accuracy. Additionally, we assess the *Bound Width* as *BoundWidth* = U ₋ $fitness - L$ ₋ $fitness$, with a smaller width indicating tighter bounds and a more accurate approximation.

We used $PI = \frac{Actual \text{ Conformance Time}}{Approximate \text{ Conformance Time}}$ to assess time performance. *Actual Conformance Time* refers to the time needed to

¹[https://github.com/lvyl9909/Approximate-Conformance-Che](https://github.com/lvyl9909/Approximate-Conformance-Checking-using-Hierarchical-Clustering.git) [cking-using-Hierarchical-Clustering.git](https://github.com/lvyl9909/Approximate-Conformance-Checking-using-Hierarchical-Clustering.git)

Figure 4: The performance differences of different selection strategies on band width and approximate error.

compute normal alignment, while *Approximate Conformance Time* includes the total time for approximation. A *PI* value greater than 1 indicates the approximation is faster than the actual conformance computation. Preprocessing time (e.g., hierarchical clustering) is included in the approximate conformance time.

6.3. Experimental Result and Discussion

Table [5](#page-6-1) shows the actual and approximate fitness values generated by comparison methods using 20% of the variants in six event logs, and for each row, we bolded the smallest values. The results show that the proposed in-cluster methods are more accurate than the baselines. Our complete experimental data is provided in [Appendix B.](#page-8-32)

	Actual Fitness	Approximate Fitness				
Event Log		Frequency	K-Medoids	In-cluster frequency	In-cluster medoid	
BPIC2012	0.9995	0.9741	0.9761	0.9788	0.9806	
BPIC2013- closed problems	0.9997	0.9860	0.9711	0.9894	0.9875	
BPIC2016- Questions	0.9997	0.9923	0.9463	0.9944	0.9565	
BPIC2017	0.9995	0.9690	0.9700	0.9749	0.9747	
Road	0.9999	0.9997	0.9996	0.9998	0.9995	
Sepsis	0.9880	0.9202	0.9202	0.9313	0.9319	

Table 5: Approximate fitness comparison for different selection methods

Figure [4](#page-6-2) shows that both *Approximate Error* and *Bound Width* decrease as selection percentages increase. Here, *Bound Width* is represented by bars, and *Approximate Error* by lines, illustrating

the improvements in these metrics as the selection percentage rises. Our in-cluster methods consistently achieve tighter bounds at each selection percentage. Notably, at a 50% selection on the BPIC2017 log, the bound widths of baseline are around 0.05, while our methods reduce this by 40% to 0.03. Additionally, across all datasets with different selection percentages, the in-cluster frequency method shows an average improvement of 19.1% in *Approximate Error* compared to the frequencybased method, while the in-cluster medoid method achieves an average improvement of 27.6% compared to the K-Medoid method. Moreover, in-cluster frequency method often produces tighter bounds than in-cluster medoid method, especially on low *Uniqueness* logs like BPIC2016-Questions, where selecting the most frequent trace is more effective than clustering. However, on high *Uniqueness* logs like *Sepsis*, in-cluster medoid method provides more accurate approximations.

In Figure [5,](#page-7-11) we compare the time performance of different log selection methods and their improvement over normal alignment. Note that a value of 1 represents the normal alignment time. Among the comparison methods, the frequency method usually results in higher performance improvement, followed by the K-Medoids method. Our methods is less efficient compared to them. Since our methods are based on hierarchical clustering, it requires step-by-step merging and calculating all possible cluster combinations, so we need more preprocessing time compared to baselines, which leads to the approximate time is higher, especially on large datasets such as BPIC2013 incidents and BPIC2017. However, even with this increase, our method remains significantly faster than the normal alignment

Figure 5: The performance improvement using different methods in six event logs

approach.

Considering both Figure [4](#page-6-2) and Figure [5,](#page-7-11) we observe a tradeoff between performance and accuracy in the proposed methods. That is, we provide more accurate bounds but need more preprocessing time to approximate the fitness.

7. CONCLUSION

In this paper, we propose an enhanced model behaviour sampling method using hierarchical clustering to construct more representative model behaviour subsets. By incorporating both frequency and control-flow information from the event log, our approach more effectively captures the model's behaviour, leading to improved approximation accuracy. Experimental results show that our method produces approximations that are on average over 19.1% closer to the actual alignment values than baseline methods, though it requires more computation time.

In future work, we plan to apply a time-optimized hierarchical clustering algorithm to reduce the approximation time of our method. Additionally, an incremental approximation tool could be developed to increase the size of model behaviour during the time, allowing the user decide when the accuracy is enough. Furthermore, exploring how to make use of the distribution information (e.g., *Uniqueness*) in the event log to choose better approximate method is also a direction for future research.

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Appendix A. Proof of Lemmas

Appendix A.1. Proof of Alignment Cost Upper Bound

Proof. We have shown that $\min_{\sigma_M \in S} \Delta(\sigma_L, \sigma_M) = \delta_S(\gamma_{SN}(\sigma_L))$ in Definition [5,](#page-2-4) so $\Delta(\sigma_L, \sigma_M) \geq \delta_S(\gamma_{SN}(\sigma_L))$. Therefore, if $\delta_S(\gamma_{SN}(\sigma_L)) > \Delta(\sigma_L, \sigma_M), \gamma_{SN}(\sigma_L)$ is not an optimal alignment. Consequently, for any $M_B \subseteq \phi_v(SN)$, $\Phi(\sigma_L, M_B)$ returns an upper bound for the cost of optimal alignment [\[5\]](#page-7-4).

Appendix A.2. Proof of Alignment Cost Lower Bound

Proof. When $|\sigma_L|_{A_v(SN)} < SPM$, at least $SPM - |\sigma_L|_{A_v(SN)}$
insertions are needed. Adding the initial alignment cost, the | insertions are needed. Adding the initial alignment cost, the total minimum alignment cost is $|SPM - \sigma_L[A_v(s_N)] + |k(\sigma_L)|$.
Similarly when $|\sigma_L[t_{v(s_N)}| > IPM$ at least $|\sigma_L[t_{v(s_N)}| = IPM$ Similarly, when $|\sigma_L|_{A_v(S,N)}| > LPM$, at least $|\sigma_L|_{A_v(S,N)}| - LPM$
deletions are required. Thus, the total alignment cost is deletions are required. Thus, the total alignment cost is $|\sigma_L|_{A_v(SN)} - LPM| + |\kappa(\sigma_L)|$. When $SPM \leq |\sigma_L|_{A_v(SN)} \leq LPM$, no insertions or deletions are needed so the alignment cost is no insertions or deletions are needed, so the alignment cost is [|]κ(σ*^L*)|.

Appendix B. Original Experimental Data

Table ?? continued. Log Actual Fitness Normal Alignment Time Candidate Percentage Parameter Approx Baseline In-cluster Frequency K-Medoids frequency In-cluster medoid BPIC2013-incident 0.9997 135400 10% Approximate fitness Lower
Bound Bound 0.9559 0.9025 0.9610 0.9560 Appr fitness 0.9780 0.9513 0.9805 0.9780 Upper Bound 1.0000 1.0000 1.0000 1.0000 $\frac{\overline{\text{Appr}}}{\underline{\text{Err}}}$ Error 10.0218 0.0485 0.0192 0.0217 Band
Width Width 0.0441 0.0975 0.0390 0.0440 Preprocessing 70923

Time (ms) / / 69233 70923 Approximate 4200 19572 2033 2992

Time (ms) 4200 19572 2033 2992

Total Approximate 4000 19572 71066 7201 al Approximate **4200** 19572 71266 73915

Time (ms) 32.2381 6.9180 1.8999 1.8318 PI 32.2381 6.9180 1.8999 1.8318 20% Approximate fitness Lower Bound 0.9719 0.9422 0.9788 0.9750 Approximate fitness 0.9860 0.9711 0.9894 0.9875 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 Approx
En Error 10.0138 0.0286 0.0103 0.0122 Band

Width 0.0281 0.0578 0.0212 0.0250

Preprocessing 1.02020 1 11426 12932

Time (ms) 11426 23054 2932 3111

Total Approximate

Total Approximate

Time (ms) 11426 23054 80944 82343 PI 11.8502 5.8732 1.6728 1.6443 30% Approximate fitness Lower
Bound Bound 0.9795 0.9554 0.9860 0.9810 Approxim
fitness fitness 0.9898 0.9777 0.9930 0.9905 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 A_p Error 10.0100 0.0220 0.0067 0.0092 Error
Band
Width Width 0.0205 0.0446 0.0140 0.0190 Preproces Preprocessing $\overline{\text{Time (ms)}}$ / 81203 85003 Approximate 17294 27553 3504 4092
Time (ms) 17204 27553 3504 4092
Total Approximate 17304 27552 84707 8000 120 Approximate 17294 27553 84707 89095

Time (ms) 17393 4.9142 1.5985 1.5197 PI 7.8293 4.9142 1.5985 1.5197 40% Approximate fitness Lower
Round Bound 0.9839 0.9612 0.9902 0.9850 Approximate fitness 0.9920 0.9806 0.9951 0.9925 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 10.0078 0.0191 0.0046 0.0072 Error
Band
Width Width 0.0161 0.0388 0.0098 0.0150 Preprocessing

Time (ms) $/$ $/$ 89129 91892 Approximate 27133 32868 3932 3902
Time (ms) 27133 32868 3932 3902
Total Approximate 27122 22868 02061 0570 al Approximate 27133 32868 93061 95794

Time (ms) 27133 32868 93061 95794

PI 4.9902 4.1195 1.4550 1.4134 PI 4.9902 4.1195 1.4550 1.4134 50% Approximate fitness Lower
Bound Bound 0.9875 0.9825 0.9920 0.9879 Approximate fitness 0.9938 0.9913 0.9960 0.9940 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 10.0060 0.0085 0.0037 0.0058 Error
Band
Width Width 0.0125 0.0175 0.0080 0.0121 Preprocessing Time (ms) / / ⁹⁵⁰⁰² ¹⁰⁴⁰²³ Approximate Time (ms) ³⁴⁰⁰⁶ ⁴¹⁰²⁸ ⁴⁰⁰² ⁴³⁵⁰ Total Approximate Time (ms) ³⁴⁰⁰⁶ ⁴¹⁰²⁸ ⁹⁹⁰⁰⁴ ¹⁰⁸³⁷³ PI 3.9817 3.3002 1.3676 1.2494

Table ?? continued. Log Actual Fitness Normal Alignment Time Candidate Percentage Parameter Approx Baseline In-cluster Frequency K-Medoids frequency In-cluster medoid BPIC2016-Questions 0.9997 5200690 10% Approximate fitness Lower
Bound Bound 0.9679 0.8867 0.9680 0.8911 Appr fitness 0.9840 0.9434 0.9840 0.9455 Upper Bound 1.0000 1.0000 0.9999 0.9999 $\frac{\overline{\text{Appr}}}{\underline{\text{Err}}}$ Error 10.0158 0.0158 0.0564 0.0158 0.0542 Band
Width Width 0.0321 0.1133 0.0319 0.1088 Preprocessing / / 359923 389454

Time(ms) Approximate 47607 61807 2715 1551
Time(ms) 1998 1999 1999 1999 2715 1551 al Approximate **47607** 61807 362638 391005

Time(ms) 109.2421 84.1440 14.3413 13.3008 109.2421 20% Approximate fitness Lower Bound 0.9845 0.8925 0.9888 0.9130 Approximate fitness 0.9923 0.9463 0.9944 0.9565 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 0.0074 0.0535 0.0053 0.0432 Band Width 0.0155 0.1075 0.0112 0.0870 Preprocessing Time(ms) / / ³⁹⁰²³⁹ ⁴²¹²⁹² Approximate Time(ms) ¹¹⁴⁷²⁷ ¹⁷⁰⁶⁶⁵ ³⁸³² ⁴⁹⁰² Total Approximate Time(ms) ¹¹⁴⁷²⁷ ¹⁷⁰⁶⁶⁵ ³⁹⁴⁰⁷¹ ⁴²⁶¹⁹⁴ PI 45.3310 30.4731 13.1973 12.2026 30% Approximate fitness Lower
Bound Bound 0.9874 0.9087 0.9920 0.9309 Approxim
fitness fitness 0.9937 0.9544 0.9960 0.9655 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 A_p Error 10.0060 0.0454 0.0037 0.0343 Error
Band
Width Width 0.0126 0.0913 0.0080 0.0691 Preprocessing

Time(ms) / / 448922 489322 Approximate 176359 266266 6020 6334
Time(ms) 176359 266266 6020 6334
Total Approximate 176250 266266 65042 40565 al Approximate 176359 266266 454942 495656

Time(ms) 29.4892 19.5319 11.4315 10.492 PI 29.4892 19.5319 11.4315 10.4925 40% Approximate fitness Lower
Round Bound 0.9896 0.9114 0.9940 0.9440 Approximate fitness 0.9948 0.9557 0.9970 0.9720 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 10.0049 0.0440 0.0027 0.0277 Error
Band
Width Width 0.0104 0.0886 0.0060 0.0560 Preprocessing / / / 483200 530239 Approximate 280456 325313 9910 10355
Time(ms) 280456 325313 9910 10355
Total Approximate 200456 225212 402110 54050 al Approximate 280456 325313 493110 540594

Time(ms) 280456 325313 493110 540594

PI 18.5437 15.9867 10.5467 9.6203 PI 18.5437 15.9867 10.5467 9.6203 50% Approximate fitness Lower
Bound Bound 0.9913 0.9294 0.9960 0.9503 Approximate fitness 0.9957 0.9647 0.9980 0.9752 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 10.0060 0.0085 0.0037 0.0058 Error
Band
Width Width 0.0125 0.0175 0.0080 0.0121 Preprocessing / / 566660 602030

Time(ms) 395799 445163 15330 14340

Total Approximate 395799 445163 15330 14340

Total Approximate 395799 445163 581990 616370 PI 13.1397 11.6827 8.9360 8.4376

13

Table ?? continued. Log Actual Fitness Normal Alignment Time Candidate Percentage Parameter Approxi Baseline In-cluster Frequency K-Medoids frequency In-cluster medoid RTFMP 0.9999 130430 10% Approximate fitness Lower Bound 0.9987 0.9975 0.9989 0.9980 Approximate fitness 0.9994 0.9988 0.9993 0.9990 Upper Bound 1.0000 1.0000 0.9997 1.0000 $\begin{tabular}{l} \hline \textbf{Appro.} \\ \hline \textbf{Err} \\ \hline \end{tabular}$ Error 10.0006 0.0011 0.0006 0.0009 Band
Width Width 0.0013 0.0025 0.0008 0.0020 Preprocessing / / 10585 11021 Approximate 8986 15555 2901 3531
Time(ms) 8986 15555 2901 3531
Total Approximate ones 15555 12406 1455 1 Approximate 8986 15555 13486 14552

Time(ms) 14.5148 8.3851 9.6715 8.9630 14.5148 20% Approximate fitness Lower Bound 0.9994 0.9991 0.9994 0.9990 Approximate fitness 0.9997 0.9996 0.9997 0.9995 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 0.0002 0.0004 0.0002 0.0004 Band Width 0.0006 0.0009 0.0006 0.0010 Preprocessing Time(ms) / / ¹⁴⁰¹² ¹⁵⁴³² Approximate Time(ms) ⁸²⁹⁶ ¹¹¹²³ ³²²¹ ³⁸³⁴ Total Approximate Time(ms) ⁸²⁹⁶ ¹¹¹²³ ¹⁷²³³ ¹⁹²⁶⁶ PI 15.7220 11.7262 7.5686 6.7700 30% Approximate fitness Lower
Bound Bound 0.9994 0.9992 0.9994 0.9994 Approxim
fitness fitness 0.9997 0.9996 0.9997 0.9997 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 A_p Error $0.0002 \t 0.0003 \t 0.0002 \t 0.0002$ Error
Band Width 0.0006 0.0008 0.0006 0.0006 0.0006 Width
Preprocess reprocessing $1 / 1$ 15236 22293 Approximate 9831 10222 3232 3923
Time(ms) 9831 10222 3232 3923
Total Approximate 0.921 10222 19469 2621 1 al Approximate 1983

Time(ms) 9831 10222 18468 26216

PI 13.2672 12.7597 7.0625 4.9752 PI 13.2672 12.7597 7.0625 4.9752 40% Approximate fitness Lower
Round Bound 0.9996 0.9993 0.9998 0.9996 Approximate fitness 0.9998 0.9997 0.9999 0.9998 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error $0.0001 \t 0.0003 \t 0.0000 \t 0.0001$ Error
Band
Width Width 0.0004 0.0007 0.0002 0.0004 Preprocessing $1 / 17222$ 24422 Approximate 10323 13123 4442 4232
Time(ms) 1998 1998 1998 13123 4442 4232 al Approximate 10323 13123 21664 28654

Time(ms) 12.6349 9.9390 6.0206 4.5519 PI 12.6349 9.9390 6.0206 4.5519 50% Approximate fitness Lower
Round Bound 0.9998 0.9996 0.9998 0.9997 Approximate fitness 0.9999 0.9998 0.9999 0.9999 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 0.0000 0.0000 0.0000 0.0000 0.0000 Error
Band
Width Width 0.0002 0.0004 0.0002 0.0003 Preprocessing Time(ms) / / ¹⁹²⁰³ ³⁰⁰²⁰ Approximate Time(ms) ⁹⁰⁵⁰ ¹⁰²¹² ⁴³⁰¹ ⁵⁰²¹ Total Approximate Time(ms) ⁹⁰⁵⁰ ¹⁰²¹² ²³⁵⁰⁴ ³⁵⁰⁴¹ PI 14.4122 12.7722 5.5493 3.7222

Table ?? continued. Log Actual Fitness Normal Alignment Time Candidate Percentage Parameter Approxi Baseline In-cluster Frequency K-Medoids frequency In-cluster medoid Sepsis 0.9880 3035200 10% Approximate fitness Lower Bound 0.7959 0.7965 0.8204 0.8100 Approximate fitness 0.8980 0.8983 0.9101 0.9050 Upper Bound 1.0000 1.0000 0.9997 1.0000 $\frac{\overline{\text{Appr}}}{\underline{\text{Err}}}$ Error 10.0901 0.0898 0.0780 0.0830 Band
Width Width 0.2041 0.2035 0.1793 0.1900 Preprocessing / / 107478 110312

Time(ms) / 107478 110312 Approximate 32599 28302 1902 2032
Time(ms) 32599 28302 1902 2032
Total Approximate 23500 38202 100280 11234 al Approximate 32599 28302 109380 112344

Time(ms) 93.1072 107.2433 27.7491 27.0170 107.2433 20% Approximate fitness Lower Bound 0.8403 0.8404 0.8626 0.8638 Approximate fitness 0.9202 0.9202 0.9313 0.9319 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 0.0679 0.0678 0.0567 0.0561 Band Width 0.1597 0.1596 0.1374 0.1362 Preprocessing Time(ms) / / ¹³⁰¹⁰¹ ¹⁴⁸⁹⁰³ Approximate Time(ms) ⁵⁶⁸⁰³ ⁶⁷⁴⁶¹ ²³⁰³ ²²⁸⁹ Total Approximate Time(ms) ⁵⁶⁸⁰³ ⁶⁷⁴⁶¹ ¹³²⁴⁰⁴ ¹⁵¹¹⁹² PI 53.4338 44.9919 22.9238 20.0751 30% Approximate fitness Lower
Bound Bound 0.8701 0.8405 0.8730 0.8748 Approxim
fitness fitness 0.9351 0.9203 0.9365 0.9374 Upper
Bound Bound 1.0000 1.0000 1.0000 1.0000 A_p Error 10.0530 0.0678 0.0515 0.0506 Error
Band Width 0.1299 0.1595 0.1270 0.1252 Width
Preprocess reprocessing $1/$ 159232 162820 Approximate 79763 60393 5201 5433
Time(ms) 79763 60393 5201 5433
Total Approximate 70252 60302 1.64432 1.6925 164433 168253

Time(ms) 79763 60393 164433 168253

PI 38.0527 50.2575 18.4586 18.0395 PI 38.0527 50.2575 18.4586 18.0395 40% Approximate fitness Lower
Round Bound 0.8931 0.8959 0.9066 0.9015 Approximate fitness 0.9466 0.9480 0.9533 0.9508 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 10.0415 0.0400 0.0347 0.0373 Error
Band
Width Width 0.1069 0.1041 0.0934 0.0985 Preprocessing / / 182782 209212 Approximate 102649 116824 6123 5736
Time(ms) 102649 116824 6123 5736
Total Approximate 102640 116824 188005 21404 al Approximate 102649 116824 188905 214948

Time(ms) 29.5687 25.9810 16.0673 14.1206 PI 29.5687 25.9810 16.0673 14.1206 50% Approximate fitness Lower
Bound Bound 0.9112 0.9113 0.9255 0.9192 Approximate fitness 0.9556 0.9557 0.9628 0.9596 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approximation Error 10.0324 0.0324 0.0253 0.0284 Error
Band
Width Width 0.0888 0.0887 0.0745 0.0808 Preprocessing / / 209823 222011

Approximate 126803 137461 3508 3769

Time(ms) 126803 137461 213331 225780

Total Approximate 126803 137461 213331 225780

Time(ms) 23.9363 22.0804 14.2277 13.4432