Enhancing Approximate Conformance Checking Accuracy with Hierarchical Clustering Model Behaviour Sampling

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Abstract

Conformance checking techniques evaluate how well a process model aligns with an actual event log. Existing methods, which rely on optimal trace alignment, are computationally intensive. To improve efficiency, a model sampling method has been proposed to construct model behaviour subset that represents the entire model. However, current model sampling techniques often lack sufficient model representativeness, limiting their potential to achieve optimal approximation accuracy. This paper proposes new model behaviour sampling approaches using hierarchical clustering to compute an approximation closer to the exact result. This paper also refines existing upper bound algorithm for better approximation. Our experiments on six real-world event logs demonstrates that our method improves approximation accuracy compared to state-of-the-art model sampling methods.

Keywords: approximate conformance checking, model behaviour sampling, hierarchical clustering, process mining

1. INTRODUCTION

Conformance checking is a set of process mining functionalities aimed at identifying deviations between the actual behaviour of the event log ("as-is") and the modeled behaviour of the process model ("to-be"). It facilitates further applications, such as model repair, anomaly detection, and algorithm evaluation [1].

In recent years, alignment-based method [2] has become the de facto standard for conformance checking in computing conformance diagnostics, as it always returns the most accurate deviations, known as optimal-alignment [3]. However, finding the optimal alignment is an NP-hard problem [4]. As the complexity of the log and model increases, the runtime complexity of optimal alignment computation grows exponentially, leading to extremely long computation times—sometimes even taking several weeks. This makes them impractical for real-world applications, especially for large-scale event logs. Moreover, in certain cases, an exact conformance value is not necessary, such as when conducting a preliminary evaluation of process models with various process discovery algorithm [5].

To tackle the problems, various approximation strategies have been proposed, including optimizing the search algorithm [6, 7] and decomposition schemes [8, 9]. However, sampling provides another angle for approximate conformance checking, such as sampling traces to represent event log [10, 11] or selecting model traces to substitute process model [5, 12]. In this paper, we adopt the latter approach, focusing on model sampling. Two main model sampling methods exist: simulation [13] and candidate selection [5]. We concentrate on candidate selection due to its higher accuracy [5]. The candidate selection method identifies representative traces from the event log (i.e. log behaviour subset), and then computes their optimal alignments to determine the corresponding model traces (i.e., model behaviour subset). The accuracy of this approximation depends on the quality of the selected log traces [12]. However, existing log selection techniques (e.g., random, frequency-based [5], K-Medoids [14]) often lack behavioural diversity and model representativeness (see Section 2), leading to reduced accuracy in conformance approximation. Hence, there is significant potential for improving the quality of model behaviour subsets.

In this paper, we propose an enhanced model behaviour sampling method to select more representative subsets and get more accuracy approximate values. First, we apply hierarchical clustering to the event log using our proposed distance criterion. Then, we propose two in-cluster methods to select typical traces from each cluster, which are then used to construct more representative model behaviour subsets. Finally, we extend existing cost lower bound algorithm to achieve more accurate approximation results. The experimental results show that our approach yields more accurate approximations than existing baselines, though with increased approximation time.

The remainder of this paper is organized as follows: Section 2 provides a motivating example to further illustrate the research problem. Section 3 discusses related work in approximate conformance checking. Section 4 outlines the necessary preliminaries. In Section 5, we propose our method for constructing model behaviour subsets using hierarchical clustering. Section 6 details the evaluation and its results. Finally, Section 7 concludes the paper and presents the future work.

2. MOTIVATING EXAMPLE

Research such as [5] and [15] has shown that selecting more typical log traces lead to higher approximation accuracy. Thus, the key challenge is determining which subset should be selected to improve approximate accuracy. Existing log selection methods, such as the frequency-based and K-medoids approaches, sometimes lack sufficient log representativeness. To illustrate the potential limitations of these methods, we use a synthesized event log L. It contains 5,106 traces consisting of 32,600 events and 12 trace variants, as shown in Table 1.

Table 1: Event Log

ID	Trace Variant	Freq	ID	Trace Variant	Freq
0	$\langle a, b, c, d, f, e, g, h \rangle$	1280	6	$\langle a, d, f, h \rangle$	250
1	$\langle a, b, c, d, e, f, g, h \rangle$	912	7	$\langle a, f, b, c \rangle$	96
2	$\langle a, b, c, d, e, g, f, h \rangle$	864	8	$\langle a, c, e, f, g \rangle$	64
3	$\langle a, b, c, h \rangle$	792	9	$\langle a, d, e, g, h \rangle$	56
4	$\langle a, b, c, d, h \rangle$	400	10	$\langle a, b, f, e, g, h \rangle$	48
5	$\langle a,h \rangle$	320	11	$\langle b, f, g \rangle$	24

To discover the event log presented in Figure 1, we applied the Inductive Miner algorithm [16] with infrequent thresholds of 0.9.



Figure 1: The Process Model discovered by Inductive Miner with infrequent threshold equals to 0.9.

Assuming we select three variants to represent the event log, i.e., the behavior subset consists of three variants. Table 2 shows the behaviour subsets generated by the frequency-based method, K-Medoids, and our proposed methods (see Section 5 for details). The frequency-based subsets shows two key limitations:

- Overestimation of Alignment Cost: Variant 5, (a, h), can be perfectly replayed in the model with an alignment cost of 0. But it's not included in our model behaviour subset, aligning it would require at least 6 insertions (i.e., cost of 6), resulting in an overestimated approximate cost.
- 2. Lack of Structural Diversity: The selected model traces $\langle a, b, c, d, f, e, g, h \rangle$ and $\langle a, b, c, d, e, f, g, h \rangle$ differ only in the order of *e* and *f*. This means they represent essentially the similar structural path, potentially overlooking other important paths in the process model.

Also, the K-Medoids method has drawbacks: it clusters traces solely based on their control-flow information, i.e., syntactic difference. For example, the trace $\langle b, f, g \rangle$ in log behaviour subset (as shown in Table 2) may have significantly syntactic differences from other traces but, due to its low frequency (only 24 occurrences), it is still not enough to represent the model behaviour.

To address the issues, our approach proposed in Section 5 effectively balances frequency and control-flow information. Table 2 also shows the cost deviation. It refers to the difference in alignment cost between using model behaviour subset and optimal-alignment. The values indicate that the model behaviours generated by our methods significantly reduce the cost deviations compared to vanilla methods.

Table 2: behaviour subsets constructed by four methods

Method	Subset	Result	Cost Deviation		
Frequency- based	Log Behaviour	$\begin{split} \Sigma_L = \{ \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, d, e, f, g, h \rangle, \\ \langle a, b, c, d, e, g, f, h \rangle \} \end{split}$	7806		
	Model Behaviour	7800			
K-Medoids	Log Behaviour	$\Sigma_L = \{ \langle a, h \rangle, \langle a, b, c, d, e, g, f, h \rangle, \\ \langle b, f, g \rangle \}$	6596		
	Model Behaviour	Behaviour $\Sigma_M = \{ \langle a, h \rangle, \langle a, b, c, d, e, g, f, h \rangle, \\ \langle a, b, e, f, g, h \rangle \}$			
In-cluster	Log Behaviour	Log Behaviour $\Sigma_L = \{\langle a, h \rangle, \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, h \rangle\}$			
frequency	Model Behaviour	$\begin{split} \Sigma_M = \{ \langle a,h\rangle, \langle a,b,c,d,f,e,g,h\rangle \\ \langle a,b,c,h\rangle \} \end{split}$	4050		
In-cluster medoid	Log Behaviour	$\Sigma_L = \{ \langle a, d, f, h \rangle, \langle a, b, c, d, f, e, g, h \rangle, \langle a, b, c, h \rangle \}$	4954		
	Model Behaviour	$\Sigma_M = \{ \langle a, d, h \rangle, \langle a, b, c, d, f, e, g, h \rangle \\ \langle a, b, c, h \rangle \}$	+66+		

3. RELATED WORK

To cope with the complexity of alignment construction, approximation techniques have been developed to balance result quality and computational cost. One approach explores fast heuristic search algorithms as alternatives to the A* algorithm [7, 17, 18]. replace the A* algorithm by exploring new fast heuristic search algorithms. One such method is Taymouri and Carmona [17], introducing an evolutionary algorithm to enhance alignment approximations. Another scheme involves decomposing models into smaller, more manageable parts, even though this may not always result in optimal alignments [19, 20]. A similar decomposition technique is discussed in [21], though it is restricted to sound and safe workflow nets. Furthermore, building automata capable of aligning log and model has been explored as another technique [22, 23]. This approach provides good approximations of the optimal alignments in most cases.

Reducing the behaviour size is another strategy for approximate conformance checking. One sampling approach focuses on sampling event log. For instance, [24] proposes a trace sampling method, assuming that a few log traces can estimate the conformance value. However, it lacks upper and lower bounds for the approximation and performs worse when the event log contains many unique behaviors.

Another sampling approach targets model behaviour. [5] introduced a model sampling method to construct subsets of model behaviour that represent the whole process model, significantly reducing approximation time while largely maintaining accuracy. The method also provides upper and lower bounds to give some certainty of the approximation.

Hierarchical clustering is widely used in process mining for its structural representativeness [25]. Additionally, [26] demonstrates how hierarchical clustering aids in discovering a better model.

4. PRELIMINARIES

This section presents conformance checking terminology and notations to support the subsequent sections. We use the basic definitions of Petri net, e.g., labeled Petri Net in [27].

Given a system net SN, $\phi_f(SN)$ is the set of all complete firing sequences of SN and $\phi_v(SN)$ is the set of all possible

visible traces, i.e., complete firing sequences starting in its initial marking and ending in its final marking projected onto the set of observable activities (not silent transitions e.g., t_3 in Figure 1).

To measure how a trace aligns to a process model, moves are represented by pairs (a, t), where a is a log activity and t is a model transition. Legal moves can be: *log moves*, *model moves*, or *synchronous moves*. Any other combination is an *illegal move*.

Definition 1. (*Alignment*). Let $\sigma_L \in L$ represent a log trace and $\sigma_M \in \phi_f(SN)$ denote a complete firing sequence of a system net SN. A_{LM} is the set of legal moves. An alignment of σ_L and σ_M is a sequence of pairs $\gamma \in A_{LM}^*$ such that the projection on the first element (ignoring \gg) yields σ_L and the projection on the second element (ignoring \gg and transition labels) yields σ_M .

To quantify the costs of alignments we introduce a cost function δ in Definition 2.

Definition 2. (*Cost of Alignment*). Cost function $\delta \in A_{LM} \rightarrow \mathbb{N}$ assigns costs to legal moves. The cost of an alignment $\gamma \in A_{LM}^*$ is the sum of all costs:

$$\delta(\gamma) = \sum_{(a,t)\in\gamma} \delta(a,t).$$

The cost values assigned to log moves, model moves, and synchronous moves are 1, 1, and 0, respectively. Note that an alignment is considered optimal if it has the minimum alignment cost.

Definition 3. (*Optimal Alignment*). Let *L* be an event log and *SN* a system net where $\phi_v(SN) \neq \emptyset$.

- For $\sigma_L \in L$, we define: $\Gamma_{\sigma_L,SN} \in \{\gamma \in A^*_{LM} \mid \exists \sigma_M \in \phi_f(SN) \text{ is an alignment of } \sigma_L \text{ and } \sigma_M \}.$
- An alignment $\gamma \in \Gamma_{\sigma_L,SN}$ is optimal for trace $\sigma_L \in L$ and system net SN if for any alignment $\gamma' \in \Gamma_{\sigma_L,M}$: $\delta(\gamma') \geq \delta(\gamma)$.
- $\gamma_{SN} \in A_{LM}^* \to A_{LM}^*$ is a mapping that assigns any log trace σ_L to an optimal alignment, i.e., $\gamma_{SN}(\sigma_L) \in \Gamma_{\sigma_L,SN}$ and $\gamma_{SN}(\sigma_L)$ is an optimal alignment.

Definition 4. (Levenshtein Edit Distance). As defined by [28], the Levenshtein edit distance $d(\sigma_1, \sigma_2) \rightarrow \mathbb{N}$ represents the minimum number of edit operations (i.e., insertions, deletions, and substitutions) required to transform one sequence into another. For instance, $d(\langle a, b \rangle, \langle c, d \rangle) = 2$, where the two edit operations are substitutions (a, c) and (b, d).

Definition 5. (*Edit Distance Cost Function*). We can calculate the distance between two traces (or sequences) faster by using a modified version of the Levenshtein edit distance [29]. Let $\sigma_1, \sigma_2 \in A^*$ be two sequences of activities. The Edit Distance Cost Function $\Delta(\sigma_1, \sigma_2) \rightarrow \mathbb{N}$ is defined as the minimum number of edits (insertion or deletion of activities) required to transform σ_1 into σ_2 .

Suppose that *S* is a set of sequences, $\Phi(\sigma_L, S) = \min_{\sigma_M \in S} \Delta(\sigma_L, \sigma_M)$ returns the distance of the most similar sequence in *S*. Let $\phi_v(SN)$ be the set of all visible firing sequences

in SN, and $\gamma_{SN}(\sigma)$ be an optimal alignment for sequence σ . It is possible to prove that $\delta_S(\gamma_{SN}(\sigma)) = \Phi(\sigma, \phi_v(SN))[12]$.

In the context of alignment, the edit distance function can be used as a cost function δ_S for evaluating the misalignment between a log trace σ_L and a model trace σ_M . This cost function assigns a value corresponding to the number of operations required to align the two sequences. For example, $\Delta(\langle a, c, b, e, d \rangle, \langle a, b, c, a, d \rangle) = 4$ corresponds to two deletions and two insertions.

Moreover, the alignment cost of a single trace can be converted into a fitness value between 0 (poor fitness, i.e., maximal costs) and 1 (perfect fitness, i.e., zero costs) using Equation 1 [5]. In this regard, we normalize this cost relative to the worst case, with one log move for each activity in the trace and one model move for each transition in the model's shortest path, $SPM = \min_{\sigma_M \in \phi_f} (|\sigma_M|)$. Here, the optimal alignment cost, $\delta(\gamma_{SN}(\sigma))$, can be replaced by an alternative cost (e.g., edit distance cost) to obtain a corresponding fitness value.

$$Fitness_{\text{Trace}}(\sigma_L, SN) = 1 - \frac{\delta_S(\gamma_{SN}(\sigma))}{|\sigma_L| + SPM}$$
(1)

Note that the overall fitness between the event log and the system net is the weighted average of single trace fitness values.

5. APPROACH

In this section, we present the proposed conformance approximation method. An overview of our approach is shown in Figure 2. The method begins with a preprocessing stage using hierarchical clustering techniques. Next, two methods are proposed for constructing model behaviour subsets: in-cluster frequency and in-cluster medoid methods. Finally, the alignment approximation process is explained.

5.1. Preprocess event log using hierarchical clustering

In this stage, we apply agglomerative hierarchical clustering [30] on event logs. Specifically, we first partition the event log based on trace variants to get the trace variant subset Σ_{σ_v} . Then, we introduce normalized weighted Levenshtein distance to measure the distance between these variants(see Definition 6) as a new in-cluster distance criterion. This criterion considers both frequency and control-flow information, alleviating the problem with current log selection methods mentioned in Section 2. It is used to build a distance matrix, then forming a dendrogram. By cutting-off the dendrogram, we obtain the desired number of clusters. The framework is illustrated in Figure 3.

Definition 6. (*Normalized Weighted Levenshtein Distance*). Let A^* be the set of all possible sequences of activities in A, and let σ_{v1}, σ_{v2} be two trace variants $\in A^*$. The normalized weighted Levenshtein distance between σ_{v1} and σ_{v2} , where each trace variant has a frequency $f(\sigma_{v1})$ and $f(\sigma_{v2})$, is defined as:

$$d_{weighted}(\sigma_{v1}, \sigma_{v2}) = \frac{f(\sigma_{v1}) \cdot f(\sigma_{v2}) \cdot d_N(\sigma_{v1}, \sigma_{v2})}{\max\{f(\sigma_{v1})^2, f(\sigma_{v2})^2\}}$$
(2)



Figure 2: Overview of our approach



Figure 3: Preprocessing workflow for hierarchical clustering

where the normalized Levenshtein distance $d_N(\sigma_{v1}, \sigma_{v2})$ is given by:

$$d_N(\sigma_{\nu 1}, \sigma_{\nu 2}) = \frac{d(\sigma_{\nu 1}, \sigma_{\nu 2})}{\max\{|\sigma_{\nu 1}|, |\sigma_{\nu 2}|\}}$$
(3)

Here, $d_N(\sigma_{v1}, \sigma_{v2}) = 0$ means the two traces are exactly the same, and $d_N(\sigma_{v1}, \sigma_{v2}) = 1$ means the two traces are completely different.

Definition 7. (*Distance Matrix*). Let $\sigma_{v1}, \sigma_{v2}, \ldots, \sigma_{vi} \in A^*$ represent all trace variants in event log L. The matrix D(L) is defined as, :

$$D(L) = \begin{bmatrix} 0 & d(\sigma_{v1}, \sigma_{v2}) & \cdots & d(\sigma_{v1}, \sigma_{vi}) \\ d(\sigma_{v2}, \sigma_{v1}) & 0 & \cdots & d(\sigma_{v2}, \sigma_{vi}) \\ \vdots & \vdots & \ddots & \vdots \\ d(\sigma_{vi}, \sigma_{v1}) & d(\sigma_{vi}, \sigma_{v2}) & \cdots & 0 \end{bmatrix}$$
(4)

where *d* is the normalized weighted Levenshtein distance function.

5.2. Constructing Model Behaviour

In this stage, we first propose two in-cluster methods to get log behaviour subset Σ_L from the generated clusters, and transform it to model behaviour subset Σ_M . Specifically,

a) Candidate selection: After preprocessing, we obtain several clusters, each representing different behaviours within the model. The following question is how to choose the typical traces from each cluster to construct a better log behaviour subset. We extend the ideas of frequency-based and medoid methods by introducing two in-cluster methods, i.e., in-cluster frequency and in-cluster medoid methods, to select trace that represents typical behaviour in each cluster as our candidate. The in-cluster frequency method selects the most frequent trace variant from each cluster. The in-cluster medoid method computes the pairwise Levenshtein distances between all traces in each cluster, then construct a distance matrix and obtain the medoid trace (see Definition 8). Note that the medoid trace is the one with the smallest total distance to all other traces in the cluster.

b) Optimal-alignment: In this step, we align Σ_L with process model to construct the Σ_M , that is, we compute the optimal alignments of selected traces in the event log and finding the corresponding model traces for these alignments.

Table 3 shows three clusters generated from the event log in Table 1. For example, applying the in-cluster frequency method to cluster 2 yields $\langle a, b, c, h \rangle^{792}$, the most frequent trace. Repeating this for each cluster, we obtain $\Sigma_L =$ $\{\langle a, b, c, d, f, e, g, h \rangle^{1280}, \langle a, b, c, h \rangle^{792}, \langle a, h \rangle^{320}\}$. We then align Σ_L with the process model as shown in Figure 1, resulting in Σ_M .Note that Σ_L and Σ_M are same in this example, as all traces can be fully replayed in the model.

Table 3: The clusters generated from the example log provided in Table 1

Cluster ID	Traces in each cluster
1	$\{\langle a,b,c,d,f,e,g,h\rangle^{1280},\langle a,b,c,d,e,f,g,h\rangle^{912},\langle a,b,c,d,e,f,g,h\rangle^{864}\}$
2	$\{\langle a,b,c,h\rangle^{792},\langle a,b,c,d,h\rangle^{400},\langle a,f,b,c\rangle^{96}\}$
3	$ \begin{aligned} & \{ \langle a,h \rangle^{320}, \langle a,d,h \rangle^{250}, \langle a,c,e,f,g \rangle^{64}, \\ & \langle a,d,e,g,h \rangle^{56}, \langle a,b,f,e,g,h \rangle^{48}, \langle b,f,g \rangle^{24} $

The specific algorithm steps for proposed methods are outlined in Algorithms 1 and 2.

Definition 8. (*In-cluster Medoid*). Let L' be a clustered sublog, n denote the number of trace variants in L', and D(L') be the distance matrix of L'. The trace $\sigma_j = \arg \min_{\sigma_j \in L'} \sum_{i \in [1,n]} d(\sigma_i, \sigma_j)$ represents the medoid trace of sublog L'.

5.3. Computing Alignment Approximation

After constructing M_B , we use it to approximate alignments for the traces in $L - L_C$, where L_C refers to the frequency-based trace variants used to build Σ_L . The actual alignment fitness for the variants in Σ_L has already been computed during the construction of M_B , so we can directly use this value for more accurate approximations. At this stage, we calculate the alignment approximations for the remaining variants.

Typically, actual fitness is calculated using standard alignment costs. However, for the remaining variants, we use the edit distance cost function Δ (see Definition 5) to estimate fitness.

Algorithm 1 In-cluster Medoid Method

Input: Event log L; Process model M.

- **Output:** Model behaviour subset Σ_M .
- 1: Initialize log behaviour subset: $\Sigma_L \leftarrow \emptyset$
- 2: Initialize model behaviour subset: $\Sigma_M \leftarrow \emptyset$
- 3: Partition *L* based on variants into Σ_{σ_v}
- Cluster Σ_{σ_ν} into k clusters {Σ_{σ_{ν1}}, Σ_{σ_{ν2}},..., Σ_{σ_{νk}}} using hierarchical clustering
- 5: **for** i = 1 to k **do**
- 6: Compute pairwise Levenshtein distances between all variants in $\Sigma_{\sigma_{vi}}$
- 7: Construct distance matrix $D(\Sigma_{\sigma_{vi}})$
- 8: Find the medoid trace $\sigma_L^{(i)}$ in $\Sigma_{\sigma_{vi}}$:

$$\sigma_{L}^{(i)} = \arg\min_{\sigma \in \Sigma_{\sigma_{vi}}} \sum_{\sigma' \in \Sigma_{\sigma_{vi}}} d(\sigma, \sigma')$$

- 9: Update log behaviour subset: $\Sigma_L \leftarrow \Sigma_L \cup \{\sigma_L^{(i)}\}$
- 10: end for
- 11: **for** each $\sigma_L^{(i)} \in \Sigma_L$ **do**
- 12: Compute optimal alignment γ_{SN}^{opt} between $\sigma_L^{(i)}$ and M13: Map to model trace: $\sigma_M^{(i)} \leftarrow \lambda_{SN}(\sigma_L^{(i)})$
- 14: Update model behaviour subset: $\Sigma_M \leftarrow \Sigma_M \cup \{\sigma_M^{(i)}\}$
- 15: **end for**
- 16: return Σ_M

Algorithm 2 In-cluster Frequency Method

Input: Event log *L*; Process model *M*.

Output: Model behaviour subset Σ_M .

1: Initialize log behaviour subset: $\Sigma_L \leftarrow \emptyset$

- 2: Initialize model behaviour subset: $\Sigma_M \leftarrow \emptyset$
- 3: Partition *L* based on variants into Σ_{σ_v}
- 4: Cluster $\Sigma_{\sigma_{v}}$ into k clusters $\{\Sigma_{\sigma_{v1}}, \Sigma_{\sigma_{v2}}, \dots, \Sigma_{\sigma_{vk}}\}$ using hierarchical clustering
- 5: **for** *i* = 1 to *k* **do**
- 6: Let $\Sigma_{\sigma_{vi}}$ denote the *i*-th cluster of variants
- 7: Find the most frequent variant $\sigma_L^{(i)}$ in $\Sigma_{\sigma_{vi}}$:

$$\sigma_L^{(i)} = \arg \max_{\sigma \in \Sigma_{\sigma_{vi}}} f(\sigma)$$

- 8: Update log behaviour subset: $\Sigma_L \leftarrow \Sigma_L \cup \{\sigma_L^{(i)}\}$ 9: end for
- 10: for each $\sigma_L^{(i)} \in \Sigma_L$ do
- 11: Compute optimal alignment γ_{SN}^{opt} between $\sigma_L^{(i)}$ and M
- 12: Map to model trace: $\sigma_M^{(i)} \leftarrow \lambda_{SN}(\sigma_L^{(i)})$
- 13: Update model behaviour subset: $\Sigma_M \leftarrow \Sigma_M \cup \{\sigma_M^{(i)}\}$
- 14: **end for**
- 15: return Σ_M

This method provides guaranteed upper and lower bounds for the alignment cost, instead of exact values [5] (see Lemma 1 and Lemma 2 below).

$$Fitness(L, SN) = \frac{\sum_{\sigma \in L_{C}} f(\sigma) \times Fitness_{\text{Approximate}}(\sigma, SN)}{\sum_{\sigma \in L} f(\sigma)} + \frac{\sum_{\sigma \in L-L_{C}} f(\sigma) \times Fitness_{\text{Actual}}(\sigma, SN)}{\sum_{\sigma \in L} f(\sigma)}$$
(5)

Lemma 1 (Alignment Cost Upper Bound). Let $\sigma_L \in \mathcal{U}_A^*$ be a log trace and $\sigma_M \in \phi_v(SN)$ be a visible firing sequence of SN. We have $\delta_S(\gamma_{SN}(\sigma_L)) \leq \Delta(\sigma_L, \sigma_M)$, where $\gamma_{SN}(\sigma_L)$ is the optimal alignment.

Proof. The proof is provided in Appendix A.1 and demonstrates how the edit distance guarantees this upper bound.

Simply put, if we align trace variant $4 \langle a, b, c, d, h \rangle$ from Table 1 with σ_L from the in-cluster frequency subset in Table 2, the alignment cost is 1 (i.e., removing "d"). However, since σ_M is a subset of the full model, the actual cost could be smaller or equal. Thus, we use 1 as the upper bound for this variant.

Lemma 2 (Alignment Cost Lower Bound). Let $SPM = \min_{\sigma_M \in \phi_v(SN)} |\sigma_M|$ and $LPM = \max_{\sigma_M \in \phi_v(SN)} |\sigma_M|$, representing the shortest and longest paths in the process model M. $\sigma_L[_{A_v(SN)}$ and $\kappa(\sigma_L)$ are as defined in Definition 9.

For any log trace σ_L , if $|\sigma_L[_{A_v(SN)}| < SPM$, the alignment cost lower bound is $SPM - |\sigma_L[_{A_v(SN)}| + \kappa(\sigma_L)$; if $|\sigma_L[_{A_v(SN)}| > LPM$, the lower bound is $|\sigma_L[_{A_v(SN)}| - LPM + \kappa(\sigma_L)$; if $SPM \le |\sigma_L[_{A_v(SN)}| \le LPM$, the lower bound is $\kappa(\sigma_L)$.

Proof. The proof is provided in Appendix A.2.

The cost lower bound is the minimum edit operations needed to transform σ_L into σ_M . We refine this algorithm using activity projection (see Definition 9) to improve approximation accuracy. Existing methods compare log trace length directly with the model's range, potentially yielding errors if irrelevant activities are present. For instance, in Figure 1, a trace $\langle a, x \rangle$ might seem aligned if its length falls within the model's shortest (SPM=2) and longest paths (LPM=8), even though x is not in the model, resulting in a miscalculated cost of 0. Our algorithm removes non-model activities (e.g., removing x from $\langle a, x \rangle$ to form $\langle a \rangle$) before comparing trace lengths. This adjustment yields a more accurate cost of 1 rather than 0, resulting in a smaller upper fitness and tighter bound width.

These bounds are then used to compute corresponding upper and lower fitness bounds (with the cost upper bound giving the fitness lower bound, and vice versa) using Equation 1. The computations for the fitness bounds are provided in Algorithm 3 and 4. The average of these bounds provides the approximate fitness. Once we compute the approximate fitness for each remaining variant, we take the weighted average of these values along with the previously computed actual fitness to get the overall approximate fitness for the entire event log, as shown in Equation 5. **Definition 9** (Activity Projection). Let $A_{\nu}(SN)$ be the set of unique observable activities in the system net SN. For any log trace σ_L , let $\sigma_L[_{A_{\nu}(SN)}$ represent the projection of σ_L onto $A_{\nu}(SN)$, meaning the set of activities in σ_L that also appear in the model. Define $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L[_{A_{\nu}(SN)}|$ as the number of activities in σ_L that are not present in the model.

For example, let $\sigma_L = \langle a, b, x \rangle$ be a log trace and the observable activities of the system net be $A_{\nu}(SN) = \{a, b, c, d, e\}$. Projecting σ_L onto $A_{\nu}(SN)$ results in $\sigma_L \lceil_{A_{\nu}(SN)} = \langle a, b \rangle$, as *x* is not part of $A_{\nu}(SN)$. Therefore, $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L \lceil_{A_{\nu}(SN)}| = 3-2 = 1$, indicating one activity in σ_L is not present in the model.

Algorithm 3 Fitness lower bound computation
Input: Event log L ; Optimal-aligned Log L_C ; Model be-
haviour subset Σ_M .
Output: Lower bound fitness $L_fitness(\sigma_L, M)$.
1: for each $\sigma_L \in L - L_C$ do
2: $\Phi(\sigma_L, \Sigma_M) //$ Compute minimum edit distance cost
3: $L_{-fitness}(\sigma_L, M) \leftarrow 1 - \frac{\Phi(\sigma_L, \Sigma_M)}{ \sigma_L + \min_{\sigma_M \in \Phi_V(SN)}(\sigma_M)}$
4: end for
5: return $L_{-}fitness(\sigma_L, M)$

Algorithm 4 Fitness upper bound computation

Input: Event log L; Optimal-aligned Log L_C ; Model behaviour subset Σ_M . **Output:** Upper bound fitness $U_{-fitness}(\sigma_L, M)$. 1: $SPM \leftarrow \min_{\sigma_M \in \phi_v(SN)} |\sigma_M| // \text{Shortest path}$ 2: $LPM \leftarrow \max_{\sigma_M \in \phi_v(SN)} |\sigma_M| // \text{Longest path}$ for each $\sigma_L \in L - L_C$ do 3: Project σ_L onto SN: $\sigma_L \lceil_{A_v(SN)}$ 4: Compute $\kappa(\sigma_L) = |\sigma_L| - |\sigma_L|_{A_v(SN)}|$ 5: if $|\sigma_L[A_{\nu}(SN)| < SPM$ then 6: $U_{-}fitness(\sigma_{L}, M) \leftarrow 1 - \frac{SPM - |\sigma_{L}[_{A_{V}(SN)}] + \kappa(\sigma_{L})}{|\sigma_{L}| + \min_{\sigma_{M} \in \Phi_{V}(SN)}(|\sigma_{M}|)}$ 7: else if $|\sigma_L[A_{\nu}(SN)| > LPM$ then 8: $U_{-fitness(\sigma_L, M)} \leftarrow 1 - \frac{|\sigma_L|_{A_V(SN)} - LPM + \kappa(\sigma_L)|}{|\sigma_L| + \min_{\sigma_M \in \phi_V(SN)} (|\sigma_M|)}$ 9: else 10: $U_{-fitness}(\sigma_L, M) \leftarrow 1 - \frac{\kappa(\sigma_L)}{|\sigma_L| + \min_{\sigma_M \in \phi_V(SN)}(|\sigma_M|)}$ 11: end if 12: 13: end for 14: return $U_{-fitness}(\sigma_L, M)$

6. EVALUATION

In this section, we assess the accuracy and time performance of our proposed log selection methods compared to frequencybased and K-Medoids techniques, and evaluate their differences in accuracy and time against normal alignment. Note that the comparison between model behaviour sampling and other approximate methods has been discussed in [5], we focus here on comparisons with the baselines of model behaviour sampling. First, we briefly describe the implementation (Section 6.1) and experimental setup (Section 6.2), followed by a discussion of the experimental results (Section 6.3).

6.1. Implementation

Our implementation consists of two steps: first, we implemented the algorithms described in Sections 5.1 and 5.2 in Python, to generate log behaviour subset from event log. Specifically, we extended the pm4py.algo.clustering package in PM4py [31] by introducing the normalized weighted Levenshtein distance (Definition 6), to perform hierarchical clustering. And implemented two proposed in-cluster methods to get the log behaviour subset based on the clustering result. In the second step, we used an existing plugin in ProM [32], *Conformance Log to Log Approximation* [33], with the generated model behaviour subset and the original event log as input, obtaining approximate fitness bounds and values. For the baselines, we used the implementation proposed by Fanisani [5]. For the normal alignment, we used PM4py to compute the time and fitness values. The source code and experimental results is available on Github ¹.

6.2. Experimental Setup

Our experiments were based on six real event logs, with the basic information about these event logs is given in Table 4. Here, *Uniqueness* refers to $\frac{Variant#}{Trace#}$. A *Uniqueness* value close to 1 indicates that almost all traces are different, e.g., *Sepsis*. For process discovery, we used *Inductive Miner infrequent algorithm* [34] with *infrequent thresholds of 0.4* to get the process model . Two log selection methods, *frequency-based sampling, K-Medoids clustering*, were used as baselines to compare with our proposed methods, i.e., *In-cluster frequency method* and *In-cluster medoid method*. Additionally, we set the *selection percentage* to 10%, 20%, 30%, 40%, and 50%, representing the ratio of selected variants to the total number of variants in the event logs. Our experiment was repeated four times since the conformance approximation time is non-deterministic. Finally, we performed the experiments on a computer with Apple M1 (8)

5 5 1									
Event Log	Activities #	Traces #	Variants #	Uniqueness					
BPIC2012 [35]	25	13087	4366	0.33					
BPIC2013-closed problems [36]	4	1487	183	0.12					
BPIC2016-Questions [37]	8	21533	2261	0.10					
BPIC2017 [38]	28	31509	15930	0.51					
Spesis [39]	18	1050	846	0.81					
RTFMP [40]	13	150370	231	0.01					

Table 4: The real-life event logs used in the experiments

6.2.1. Evaluation Metrics

cores), 8 GB RAM running macOS.

To measure approximation accuracy, we used *Approximate* Error, defined as *ApproximateError* = |ActualFitness - ApproximateFitness|, where a value closer to 0 indicates higher accuracy. Additionally, we assess the *Bound Width* as *BoundWidth* = $U_{-}fitness - L_{-}fitness$, with a smaller width indicating tighter bounds and a more accurate approximation.

We used $PI = \frac{Actual Conformance Time}{Approximate Conformance Time}$ to assess time performance. Actual Conformance Time refers to the time needed to

¹https://github.com/lvy19909/Approximate-Conformance-Che cking-using-Hierarchical-Clustering.git



Figure 4: The performance differences of different selection strategies on band width and approximate error.

compute normal alignment, while *Approximate Conformance Time* includes the total time for approximation. A *PI* value greater than 1 indicates the approximation is faster than the actual conformance computation. Preprocessing time (e.g., hierarchical clustering) is included in the approximate conformance time.

6.3. Experimental Result and Discussion

Table 5 shows the actual and approximate fitness values generated by comparison methods using 20% of the variants in six event logs, and for each row, we bolded the smallest values. The results show that the proposed in-cluster methods are more accurate than the baselines. Our complete experimental data is provided in Appendix B.

Event Leg	A atual Fitness	Approximate Fitness							
Event Log	Actual Filless	Frequency	K-Medoids	In-cluster	In-cluster				
				requency	medola				
BPIC2012	0.9995	0.9741	0.9761	0.9788	0.9806				
BPIC2013-	0 9997	0.9860	0.9711	0 9894	0.9875				
closed problems	0.9997	0.9800	0.9711	0.2024	0.2075				
BPIC2016-	0 9997	0.0023	0.9463	0 9944	0.9565				
Questions	0.7777	0.7725	0.9405	0.5544	0.7505				
BPIC2017	0.9995	0.9690	0.9700	0.9749	0.9747				
Road	0.9999	0.9997	0.9996	0.9998	0.9995				
Sepsis	0.9880	0.9202	0.9202	0.9313	0.9319				

Table 5: Approximate fitness comparison for different selection methods

Figure 4 shows that both *Approximate Error* and *Bound Width* decrease as selection percentages increase. Here, *Bound Width* is represented by bars, and *Approximate Error* by lines, illustrating

the improvements in these metrics as the selection percentage rises. Our in-cluster methods consistently achieve tighter bounds at each selection percentage. Notably, at a 50% selection on the BPIC2017 log, the bound widths of baseline are around 0.05, while our methods reduce this by 40% to 0.03. Additionally, across all datasets with different selection percentages, the in-cluster frequency method shows an average improvement of 19.1% in Approximate Error compared to the frequencybased method, while the in-cluster medoid method achieves an average improvement of 27.6% compared to the K-Medoid method. Moreover, in-cluster frequency method often produces tighter bounds than in-cluster medoid method, especially on low Uniqueness logs like BPIC2016-Questions, where selecting the most frequent trace is more effective than clustering. However, on high Uniqueness logs like Sepsis, in-cluster medoid method provides more accurate approximations.

In Figure 5, we compare the time performance of different log selection methods and their improvement over normal alignment. Note that a value of 1 represents the normal alignment time. Among the comparison methods, the frequency method usually results in higher performance improvement, followed by the K-Medoids method. Our methods is less efficient compared to them. Since our methods are based on hierarchical clustering, it requires step-by-step merging and calculating all possible cluster combinations, so we need more preprocessing time compared to baselines, which leads to the approximate time is higher, especially on large datasets such as BPIC2013incidents and BPIC2017. However, even with this increase, our method remains significantly faster than the normal alignment



Figure 5: The performance improvement using different methods in six event logs

approach.

Considering both Figure 4 and Figure 5, we observe a tradeoff between performance and accuracy in the proposed methods. That is, we provide more accurate bounds but need more preprocessing time to approximate the fitness.

7. CONCLUSION

In this paper, we propose an enhanced model behaviour sampling method using hierarchical clustering to construct more representative model behaviour subsets. By incorporating both frequency and control-flow information from the event log, our approach more effectively captures the model's behaviour, leading to improved approximation accuracy. Experimental results show that our method produces approximations that are on average over 19.1% closer to the actual alignment values than baseline methods, though it requires more computation time.

In future work, we plan to apply a time-optimized hierarchical clustering algorithm to reduce the approximation time of our method. Additionally, an incremental approximation tool could be developed to increase the size of model behaviour during the time, allowing the user decide when the accuracy is enough. Furthermore, exploring how to make use of the distribution information (e.g., *Uniqueness*) in the event log to choose better approximate method is also a direction for future research.

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Appendix A. Proof of Lemmas

Appendix A.1. Proof of Alignment Cost Upper Bound

Proof. We have shown that $\min_{\sigma_M \in S} \Delta(\sigma_L, \sigma_M) = \delta_S(\gamma_{SN}(\sigma_L))$ in Definition 5, so $\Delta(\sigma_L, \sigma_M) \ge \delta_S(\gamma_{SN}(\sigma_L))$. Therefore, if $\delta_S(\gamma_{SN}(\sigma_L)) > \Delta(\sigma_L, \sigma_M), \gamma_{SN}(\sigma_L)$ is not an optimal alignment. Consequently, for any $M_B \subseteq \phi_v(SN), \Phi(\sigma_L, M_B)$ returns an upper bound for the cost of optimal alignment [5].

Appendix A.2. Proof of Alignment Cost Lower Bound

Proof. When $|\sigma_L[_{A_v(SN)}| < SPM$, at least $SPM - |\sigma_L[_{A_v(SN)}|$ insertions are needed. Adding the initial alignment cost, the total minimum alignment cost is $|SPM - \sigma_L[_{A_v(SN)}| + |\kappa(\sigma_L)|$. Similarly, when $|\sigma_L[_{A_v(SN)}| > LPM$, at least $|\sigma_L[_{A_v(SN)}| - LPM$ deletions are required. Thus, the total alignment cost is $|\sigma_L[_{A_v(SN)}-LPM| + |\kappa(\sigma_L)|$. When $SPM \le |\sigma_L[_{A_v(SN)}| \le LPM$, no insertions or deletions are needed, so the alignment cost is $|\kappa(\sigma_L)|$.

Appendix B. Original Experimental Data

	Actual Fitness	tual Normal Alignment Time	Candidate Percentage			Approximation Method Baseline In-cluster medoid			
Log				Para	meter	Frequency	K-Medoids	In-cluster frequency	In-cluster medoid
					Lower	0.9167	0.9371	0.9368	0.9416
				Approximate	Approximate	0.9583	0.9685	0.9684	0.9708
				ntness	Upper	1.0000	1.0000	1.0000	1.0000
				Approx	dimation	0.0412	0.0310	0.0311	0.0287
				Er Ba	Error Band		0.0620	0.0511	0.0584
			10%	Prepro	idth cessing	0.0855	0.0029	1210022	1250201
				Time	e (ms) oximate	/	/	1219923	1259201
				Time Total An	e (ms) proximate	411778	439928	25030	26102
				Time	e (ms)	411778	439928	1244953	1285303
					Lower	0.9482	0.9522	0.9576	0.9612
				Approximate	Approximate	0.9741	0.9761	0.9788	0.9806
				ntness	Upper	1.0000	1.0000	1.0000	1.0000
				Approx	Bound	0.0254	0.0234	0.0207	0.0189
				Er Ba	ror and	0.0519	0.02.54	0.0207	0.0289
			20%	Prepro	idth cessing	0.0518	0.0478	0.0424	0.0388
				Time	e (ms) eximate	/	/	1342972	1392321
		3540000		Time (ms)		572356	859792	39232	32323
				Time (ms)		572356	859792	1382204	1424644
					Lower	0.9618	0.9629	0.9688	0.9702
				Approximate fitness	Approximate	0.9809	0.9814	0.9844	0.9851
					Upper	1.0000	1.0000	1.0000	1.0000
				Approx	Bound	0.0186	0.0181	0.0151	0.0144
	0.9995			Error Band		0.0282	0.0271	0.0212	0.0109
			30%	Width Preprocessing		0.0382	0.0571	1422210	1520212
BPIC2012				Time (ms) Approximate		/	/	1423219	1529312
				Time (ms) Total Approximate		702244	1186892	41992	42223
				Time (ms)		702244	1186892 29.8258	24 1603	22 5257
					Lower	0.9681	0.9690	0.9756	0.9730
				Approximate	Approximate	0.9841	0.9845	0.9878	0.9865
				fitness	Upper	1.0000	1.0000	1.0000	1.0000
				Approx	cimation	0.0155	0.0150	0.0117	0.0130
			400%	Ba	and	0.0319	0.0310	0.0244	0.0270
			40%	Prepro	cessing	/	/	1591211	1730030
				Time	e (ms) oximate	1229401	1480757	41503	49020
				Time Total Ap	e (ms) proximate	1220401	1400757	1622714	1770050
				Time	e (ms) PI	28.7945	23.9067	21.6817	19.8983
					Lower Bound	0.9745	0.9752	0.9802	0.9888
				Approximate fitness	Approximate	0.9873	0.9876	0.9901	0.9944
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Approx	cimation	0.0123	0.0119	0.0094	0.0051
			50%	Ba	and	0.0255	0.0248	0.0198	0.0112
			50 10	Prepro	cessing	/	/	1823900	2102097
				Appro	e (ms) oximate	1863573	1971131	42826	43503
				Time Total Ap	proximate	1863573	1971131	1866726	2145600
				Time (ms) PI		18.9958	17.9592	18.9637	16.4989

	Actual Fitness	ctual Normal Alignment Time	a rite	Parameter		Approximation Method Baseline In-cluster medoid			
Log			Percentage			Eraquanay	K Madaida	In-cluster	In-cluster
			-		Laura	Frequency	K-iviedoids	frequency	medoid
					Bound	0.9559	0.9025	0.9610	0.9560
				Approximate fitness	Approximate	0.9780	0.9513	0.9805	0.9780
				naloss	Upper	1.0000	1.0000	1.0000	1.0000
				Approx	Bound cimation	1.0000	1.0000	1.0000	1.0000
				Er	TOF	0.0218	0.0485	0.0192	0.0217
			10%	Wi	idth	0.0441	0.0975	0.0390	0.0440
				Prepro	cessing	/	/	69233	70923
				Appro	oximate	4200	19572	2033	2992
				Time Total Ap	e (ms) proximate				
				Time	e (ms)	4200	19572	71266	73915
					Lower	0.0710	0.9180	0.0788	0.0750
				Approximate	Bound	0.9719	0.9422	0.9788	0.9750
				fitness	fitness	0.9860	0.9711	0.9894	0.9875
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Approx	cimation	0.0138	0.0286	0.0103	0.0122
				Ba	and	0.0281	0.0578	0.0212	0.0250
			20%	Prepro	idth cessing	0.0281	0.0578	0.0212	0.0250
				Time	e (ms)	/	/	78012	79232
				Appro	eximate (ms)	11426	23054	2932	3111
				Total Approximate		11426	23054	80944	82343
				Iime	e (ms) PI	11.8502	5.8732	1.6728	1.6443
					Lower	0.9795	0.9554	0.9860	0.9810
				Approximate fitness	Approximate	0.0808	0.9777	0.9930	0.9905
					fitness	0.7070	0.9111	0.7750	0.7705
					Bound	1.0000	1.0000	1.0000	1.0000
				Approximation Error		0.0100	0.0220	0.0067	0.0092
			30%	Band		0.0205	0.0446	0.0140	0.0190
			50%	Preprocessing		,	1	81202	85002
BPIC2013-incident	0.9997	135400		Time (ms) Approximate		/	/	81205	85005
				Time (ms)		17294	27553	3504	4092
				Total Approximate Time (ms)		17294	27553	84707	89095
				I	PI	7.8293	4.9142	1.5985	1.5197
					Bound	0.9839	0.9612	0.9902	0.9850
				Approximate fitness	Approximate	0.9920	0.9806	0.9951	0.9925
					Upper	1.0000	1.0000	1.0000	1.0000
				Approx	dimation	0.0070	0.0101	0.0046	0.0070
				Er D.	ror and	0.0078	0.0191	0.0046	0.0072
			40%	Wi	idth	0.0161	0.0388	0.0098	0.0150
				Prepro Time	cessing e (ms)	/	/	89129	91892
				Appro	oximate	27133	32868	3932	3902
				Total Ap	proximate	27122	22868	02061	05704
				Time	e (ms)	4 0002	4 1105	1 4550	93794
					Lower	0.9875	0,9825	0,9920	0,9879
				Approximate	Bound Approximate	0.0	0.0	0.07-77	0.07.17
				fitness	fitness	0.9938	0.9913	0.9960	0.9940
					Bound	1.0000	1.0000	1.0000	1.0000
				Approx	cimation Tor	0.0060	0.0085	0.0037	0.0058
			50%	Ba	and	0.0125	0.0175	0.0080	0.0121
			50%	Prepro	idth cessing			0.0000	10/777
				Time	e (ms)	/	/	95002	104023
				Appro	e (ms)	34006	41028	4002	4350
				Total Ap	proximate (ms)	34006	41028	99004	108373
				IIII	PI	3.9817	3.3002	1.3676	1.2494

	Actual	tual Normal Alignment	Candidate Percentage	Parameter		Approximation Method			
Log						Bas	eline	In-cluster	r medoid In-cluster
		Time				Frequency	K-Medoids	frequency	medoid
					Lower Bound	0.9679	0.8867	0.9680	0.8911
				Approximate	Approximate	0.9840	0.9434	0.9840	0.9455
				fitness	fitness Upper				
					Bound	1.0000	1.0000	0.9999	0.9999
				Approx	cimation Tor	0.0158	0.0564	0.0158	0.0542
			10%	Ba	and	0.0321	0.1133	0.0319	0.1088
			10%	Prepro	cessing		1	250022	200454
				Tim	e(ms)	/	/	339923	369434
				Tim	e(ms)	47607	61807	2715	1551
				Total Ap Tim	proximate e(ms)	47607	61807	362638	391005
				1	PI	109.2421	84.1440	14.3413	13.3008
					Lower Bound	0.9845	0.8925	0.9888	0.9130
				Approximate	Approximate	0.9923	0.9463	0.9944	0.9565
				ntness	Upper	1.0000	1.0000	1.0000	1.0000
				A	Bound	1.0000	1.0000	1.0000	1.0000
				E	Tor	0.0074	0.0535	0.0053	0.0432
			20%	Ba	and	0.0155	0.1075	0.0112	0.0870
				Width Preprocessing		/	/	300230	421202
				Tim	e(ms) oximate	/	/	570257	
				Time(ms)		114727	170665	3832	4902
				Tim	e(ms)	114727	170665	394071	426194
				1	PI	45.3310	30.4731	13.1973	12.2026
				Approximate fitness	Bound	0.9874	0.9087	0.9920	0.9309
					Approximate	0.9937	0.9544	0.9960	0.9655
					Upper	1.0000	1.0000	1.0000	1.0000
				Approx	Bound Gimation	0.0050	0.0454	0.0007	0.0242
				Error		0.0060	0.0454	0.0037	0.0343
			30%	Width		0.0126	0.0913	0.0080	0.0691
				Preprocessing Time(ms)		/	/	448922	489322
BPIC2016-Questions	0.9997	5200690		Approximate		176359	266266	6020	6334
				Time(ms) Total Approximate		17/2/20	244244	151010	105555
				Time(ms)		176359	266266	454942	495656
				1	Lower	29.4892	19.5319	0.0040	10.4925
				Approvimate	Bound	0.9890	0.9114	0.9940	0.9440
				fitness	fitness	0.9948	0.9557	0.9970	0.9720
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Approx	cimation	0.0049	0.0440	0.0027	0.0277
			100	B	and	0.0104	0.0886	0.0060	0.0560
			40%	Prepro	idth cessing	0.0104	0.0000	0.0000	0.0500
				Tim	e(ms)	/	/	483200	530239
				Appro	e(ms)	280456	325313	9910	10355
				Total Ap	proximate	280456	325313	493110	540594
					PI	18.5437	15.9867	10.5467	9.6203
					Lower	0.9913	0.9294	0.9960	0.9503
				Approximate	Approximate	0,9957	0,9647	0,9980	0,9752
				htness	titness Upper	1.0000	1.0000	1.0000	1.0000
				A	Bound	1.0000	1.0000	1.0000	1.0000
				Approx	TOF	0.0060	0.0085	0.0037	0.0058
			50%	Ba	and idth	0.0125	0.0175	0.0080	0.0121
				Prepro	cessing	/	/	566660	602030
				Tim	e(ms) oximate	205700	145152	15220	14240
				Tim Total A =	e(ms)	393799	445163	15330	14340
				Tim	e(ms)	395799	445163	581990	616370
1	1		1		PI	13.1397	11.6827	8.9360	8.4376

Table ?? continued. Approximation Method Normal Baseline In-cluster medoid Actual Candidate Log Alignment Time Parameter In-cluster In-cluster Fitness Percentage K-Medoids Frequency frequency medoid Lower Bound Approxima 0.9332 0.9381 0.9454 0.9450 Approximate fitness 0.9726 0.9725 0.9666 0.9691 fitness Upper 1.0000 1.0000 0.9997 1.0000 Bound Approximation Approximation Error Band Width Preprocessing Time (ms) 0.0329 0.0305 0.0270 0.0270 0.0668 0.0619 0.0543 0.0550 10% 86490212 87983292 1 / Approximate 4049416 4399280 400366 509232 Time (ms) Total Approximate Time (ms) PI 4049416 4399280 86890578 88492524 44.6556 41.1043 2.0811 2.0434 Lower 0.9380 0.9399 0.9497 0.9493 Bound Approximate Approximate fitness 0.9690 0.9700 0.9749 0.9747 fitness Upper Bound 1.0000 1.0000 1.0000 1.0000 Approxima Error Band on 0.0305 0.0296 0.0247 0.0249 0.0620 0.0601 0.0503 0.0507 20% Width Preprocessing 91423432 95431122 1 1 Time(ms) Time(ms) Approximate Time(ms) Total Approximate Time(ms) PI 15255832 18597920 424210 561543 15255832 18597920 91847642 95992665 11.8531 9.7231 1.9688 1.8838 Lower 0.9512 0.9431 0.9420 0.9510 Bound Approximate fitness Approximate fitness 0.9715 0.9710 0.9755 0.9756 Upper Bound 1.0000 1.0000 1.0000 1.0000 Approxima Error Band 0.0280 0.0285 0.0240 0.0239 0.0569 0.0580 0.0488 0.0490 30% Width Preprocessing 1 1 95294232 99874342 Time(ms) Approximate Time(ms) Total Approximate BPIC2017 0.9995 180829300 13089388 16606568 502321 424931 13089388 16606568 95796553 100299273 Time(ms) 10.8890 13.8150 1.8029 1.8876 PI Lower 0.9481 0.9480 0.9575 0.9564 Bound Approxim fitness Upper Approximate fitness 0.9741 0.9740 0.9788 0.9782 1.0000 1.0000 1.0000 1.0000 Bound Approximation 0.0255 0.0255 0.0213 0.0208 Error Band 40% 0.0519 0.0520 0.0425 0.0436 Width Preprocessing Time(ms) Approximate 99034313 100293122 16294010 18807577 582312 510124 Time(ms) Total Approximate 16294010 18807577 99616625 100803246 Time(ms) 11.0979 9.6147 1.8153 1.7939 Lower Bound Approximate 0.9528 0.9527 0.9682 0.9691 Approximate fitness 0.9764 0.9764 0.9841 0.9846 fitness Upper 1.0000 1.0000 1.0000 1.0000 Approximation Approximation Error Band Width Preprocessing Time(ms) Approximate Time(ms) 0.0231 0.0232 0.0154 0.0150 0.0472 0.0473 0.0318 0.0309 50% 108224313 119901232 1 20183838 22539508 391222 454002 Total Approximate Time(ms) PI 20183838 22539508 108615535 120355234 8.9591 8.0228 1.6649 1.5025

	Actual Fitness	ual Normal Alignment Time	Candidate Percentage	Parameter		Approximation Method Baseline In-cluster medoid			
Log						Frequency	K-Medoids	In-cluster	In-cluster
					Lower	Trequency	R-Medold3	frequency	medoid
					Bound	0.9987	0.9975	0.9989	0.9980
				Approximate fitness	Approximate fitness	0.9994	0.9988	0.9993	0.9990
					Upper	1.0000	1.0000	0.9997	1.0000
				Approx	Bound	0.0000	0.0011	0.0007	0.0000
				Er	Error		0.0011	0.0006	0.0009
			10%	Wi	idth	0.0013	0.0025	0.0008	0.0020
				Prepro Tim	cessing e(ms)	/	/	10585	11021
				Appro	ximate	8986	15555	2901	3531
				Total Ap	proximate	8086	15555	12496	14552
				Tim	e(ms)	14 5148	8 3851	9.6715	8 9630
					Lower	0.9994	0.9991	0.9994	0.9990
				Approximate	Approximate	0.0007	0.0000	0.0007	0.0005
				fitness	fitness	0.9997	0.9996	0.9997	0.9995
					Bound	1.0000	1.0000	1.0000	1.0000
				Approx	timation	0.0002	0.0004	0.0002	0.0004
			2007	Ba	and	0.0006	0.0009	0.0006	0.0010
			20%	Prepro	idth cessing				
				Time	e(ms)	/	/	14012	15432
				Time(ms)		8296	11123	3221	3834
				Total Approximate Time(ms)		8296	11123	17233	19266
				l	2[2]	15.7220	11.7262	7.5686	6.7700
					Lower Bound	0.9994	0.9992	0.9994	0.9994
				Approximate	Approximate	0.9997	0.9996	0.9997	0.9997
				nucess	Upper	1.0000	1.0000	1.0000	1.0000
	0.9999			Approx	Bound	1.0000	1.0000	1.0000	1.0000
				Error		0.0002	0.0003	0.0002	0.0002
			30%	Band Width		0.0006	0.0008	0.0006	0.0006
		130430		Preprocessing		/	/	15236	22293
RTFMP				Approximate		0921	10222	2222	2022
				Time(ms) Total Approximate		2051	10222	5252	5725
				Time(ms)		9831	10222	18468	26216
				1	Lower	13.2672	12./59/	7.0625	4.9752
				Approximate	Bound	0.9996	0.9995	0.9998	0.9996
				fitness	fitness	0.9998	0.9997	0.9999	0.9998
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Approx	imation	0.0001	0.0003	0.0000	0.0001
				Ba	and	0.0004	0.0007	0.0002	0.0004
			40%	Prepro	idth cessing	0.0001	0.0007	0.0002	0.0001
				Tim	e(ms)	/	/	17222	24422
				Appro	e(ms)	10323	13123	4442	4232
				Total Ap	proximate	10323	13123	21664	28654
				I	PI	12.6349	9.9390	6.0206	4.5519
					Lower Bound	0.9998	0.9996	0.9998	0.9997
				Approximate	Approximate	0.9999	0.9998	0.9999	0.9999
				nuless	Upper	1.0000	1.0000	1.0000	1.0000
				Δηρεοι	Bound	1.0000	1.0000	1.0000	1.0000
				Er	TOP	0.0000	0.0001	0.0000	0.0000
			50%	Ba Wi	and idth	0.0002	0.0004	0.0002	0.0003
			50%	Prepro	Width Preprocessing		/	19203	30020
				Appro	ximate	0050	10212	4301	5021
				Time Total An	e(ms) proximate	5050	10212	4.301	5021
				Tim	e(ms)	9050	10212	23504	35041
1	1	1	1		4	14.4122	12.7722	5.5493	3.7222

	Actual Fitness	l Normal Alignment Time	Candidate Percentage			Approximation Method Baseline Incluster medoid			
Log				Para	Parameter		K Madaida	In-cluster	In-cluster
					Lower	Frequency	K-Weddids	frequency	medoid
					Bound	0.7959	0.7965	0.8204	0.8100
				Approximate fitness	Approximate	0.8980	0.8983	0.9101	0.9050
					Upper	1.0000	1.0000	0.9997	1.0000
				Approx	Bound Cimation				
				Ei	TOF	0.0901	0.0898	0.0780	0.0830
			10%	W	idth	0.2041	0.2035	0.1793	0.1900
				Prepro	cessing e(ms)	/	/	107478	110312
				Appro	oximate	32599	28302	1902	2032
				Tim Total Ap	e(ms) proximate				
				Tim	e(ms)	32599	28302	109380	112344
					Lower	95.1072	0.8404	0.8626	0.8638
				Approximate	Bound	0.8405	0.8404	0.8020	0.8038
				fitness	fitness	0.9202	0.9202	0.9313	0.9319
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Approx	cimation	0.0679	0.0678	0.0567	0.0561
				B	and	0.1507	0.1506	0.1274	0.1262
			20%	Prento	idth cessing	0.1597	0.1596	0.1374	0.1362
				Tim	e(ms)	/	/	130101	148903
				Appro	Approximate Time(ms)		67461	2303	2289
				Total Approximate		56803	67461	132404	151192
				Tim	e(ms) PI	53.4338	44.9919	22.9238	20.0751
					Lower	0.8701	0.8405	0.8730	0.8748
			306	Approximate	Approximate	0.9351	0.9203	0.9365	0.9374
				fitness	fitness	0.7551	0.7205	0.7505	0.7514
					Bound	1.0000	1.0000	1.0000	1.0000
				Approximation Error		0.0530	0.0678	0.0515	0.0506
				Band		0.1299	0.1595	0.1270	0.1252
				Preprocessing		/	/	150232	162820
Sepsis	0.9880	3035200		Time(ms) Approximate		/	1	139232	102020
				Time(ms)		79763	60393	5201	5433
				Total Approximate Time(ms)		79763	60393	164433	168253
				1	PI	38.0527	50.2575	18.4586	18.0395
					Bound	0.8931	0.8959	0.9066	0.9015
				Approximate fitness	Approximate fitness	0.9466	0.9480	0.9533	0.9508
					Upper	1.0000	1.0000	1.0000	1.0000
				Approx	dimation	0.0415	0.0400	0.0247	0.0272
				Ei	TOF	0.0415	0.0400	0.0347	0.0373
			40%	W	idth	0.1069	0.1041	0.0934	0.0985
				Prepro	cessing e(ms)	/	/	182782	209212
				Appro	oximate	102649	116824	6123	5736
				Tim Total Ap	e(ms) proximate	102640	116924	199005	214048
				Tim	e(ms)	20 5687	25 0810	16 0673	14 1206
					Lower	0.9112	0.9113	0.9255	0.9192
				Approximate	Bound	0.9112	0.9115	0.9255	0.9192
				fitness	fitness	0.9556	0.9557	0.9628	0.9596
					Upper Bound	1.0000	1.0000	1.0000	1.0000
				Approx	cimation Tor	0.0324	0.0324	0.0253	0.0284
				B	and	0.0888	0.0887	0.0745	0.0808
			50%	Prento	idth cessing	0.0000	0.0007	0.0745	0.0000
				Tim	e(ms)	/	/	209823	222011
				Appro	e(ms)	126803	137461	3508	3769
				Total Ap	proximate	126803	137461	213331	225780
				11m	PI	23.9363	22.0804	14.2277	13.4432